

MathWorks AUTOMOTIVE CONFERENCE 2022 India

Software-Defined Vehicles: Workflows for In-Car and Cloud Applications

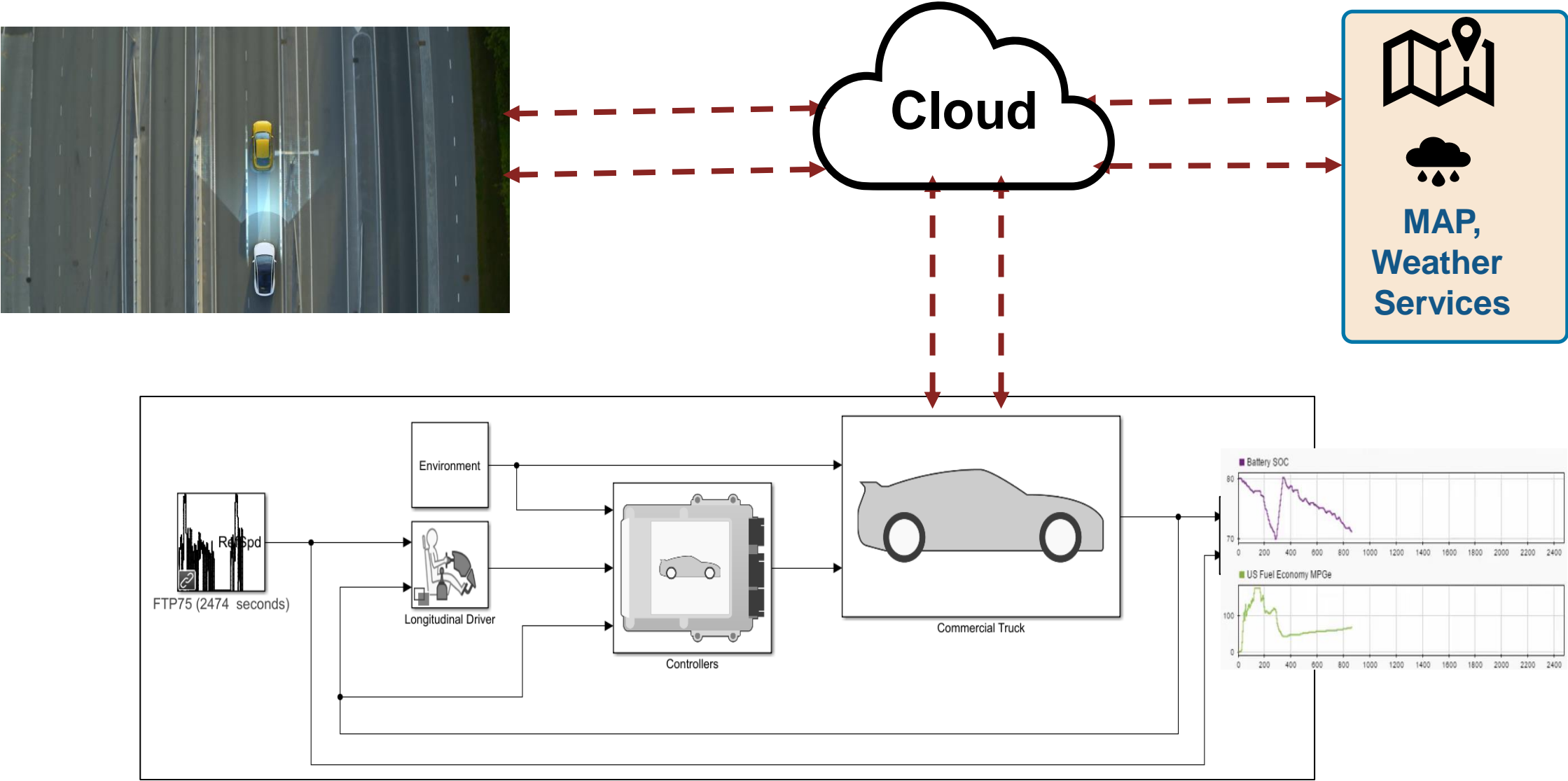
Prasanna Deshpande, MathWorks



Nukul Sehgal, MathWorks



Application design for Autonomous Electric Vehicle



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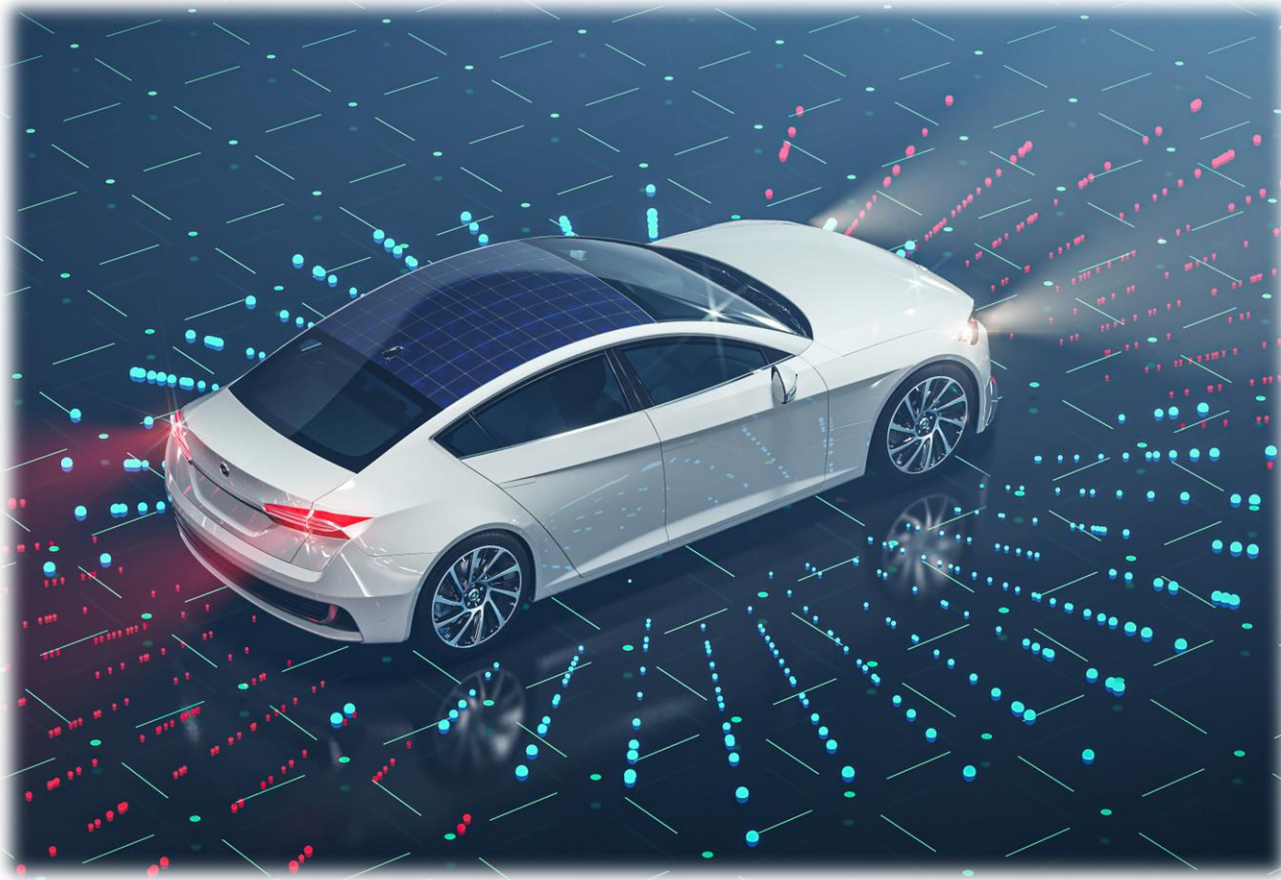
Software-Defined Vehicles: Workflows for In-Car and Cloud Applications

Prasanna Deshpande, MathWorks



Nukul Sehgal, MathWorks





Brand-distinctive
features and main
value for the
vehicle will come
from Software

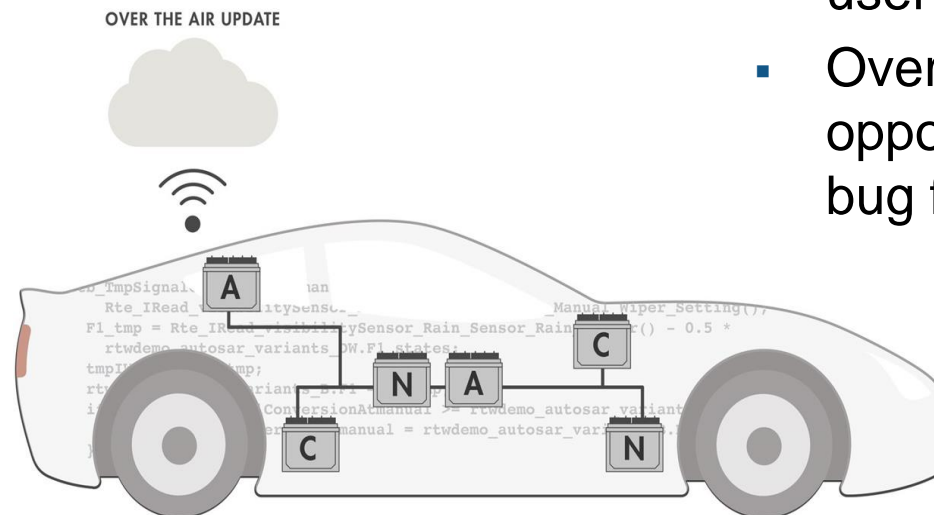
Value of Software-Defined Vehicle

For the user

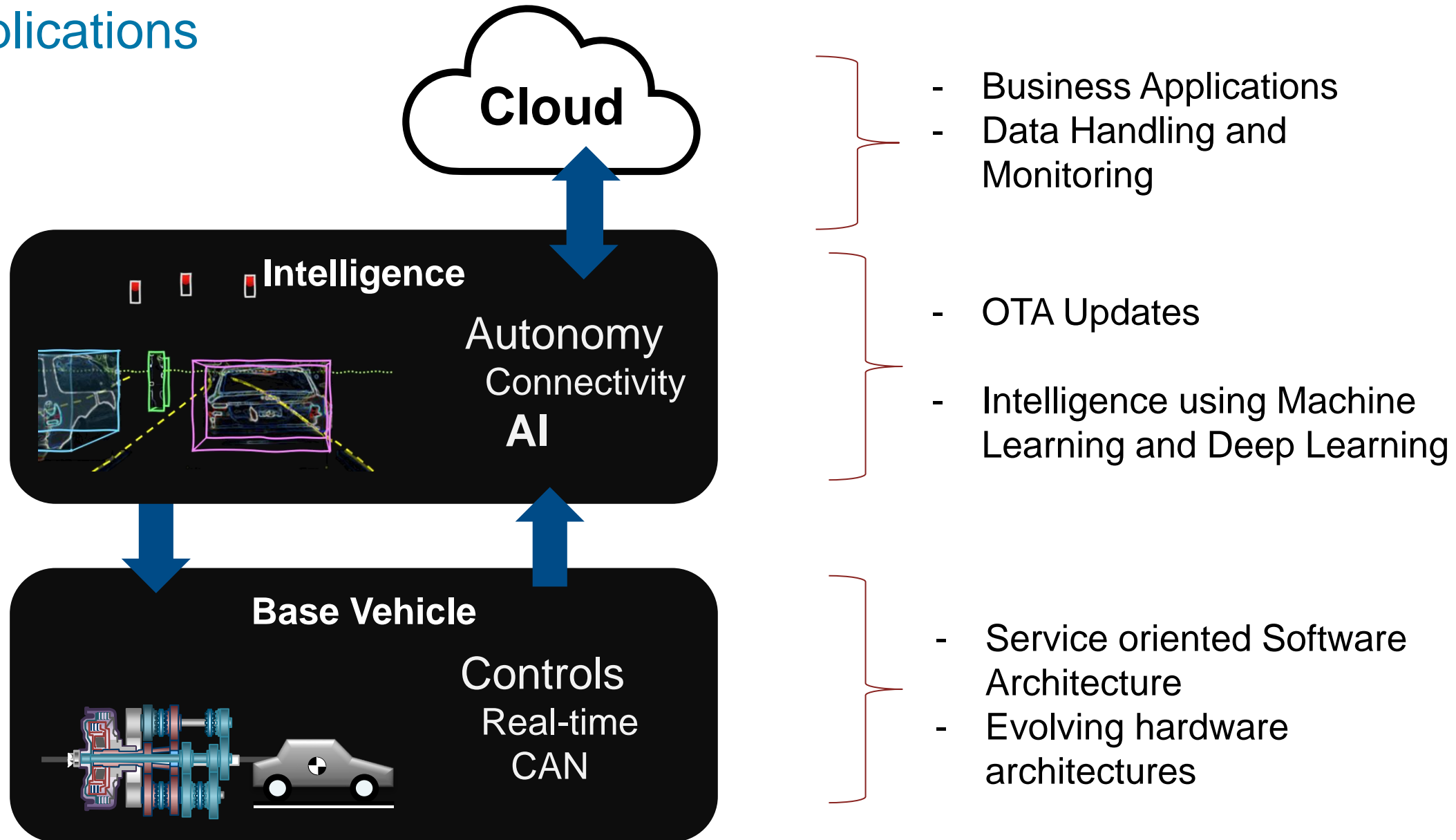
- A vehicle that can have features added to and removed from it, throughout its life
- My vehicle is tailored for my needs
- Smartphone on wheels
- Better and better for me as it collects my data, I get features that add value to me

For the maker

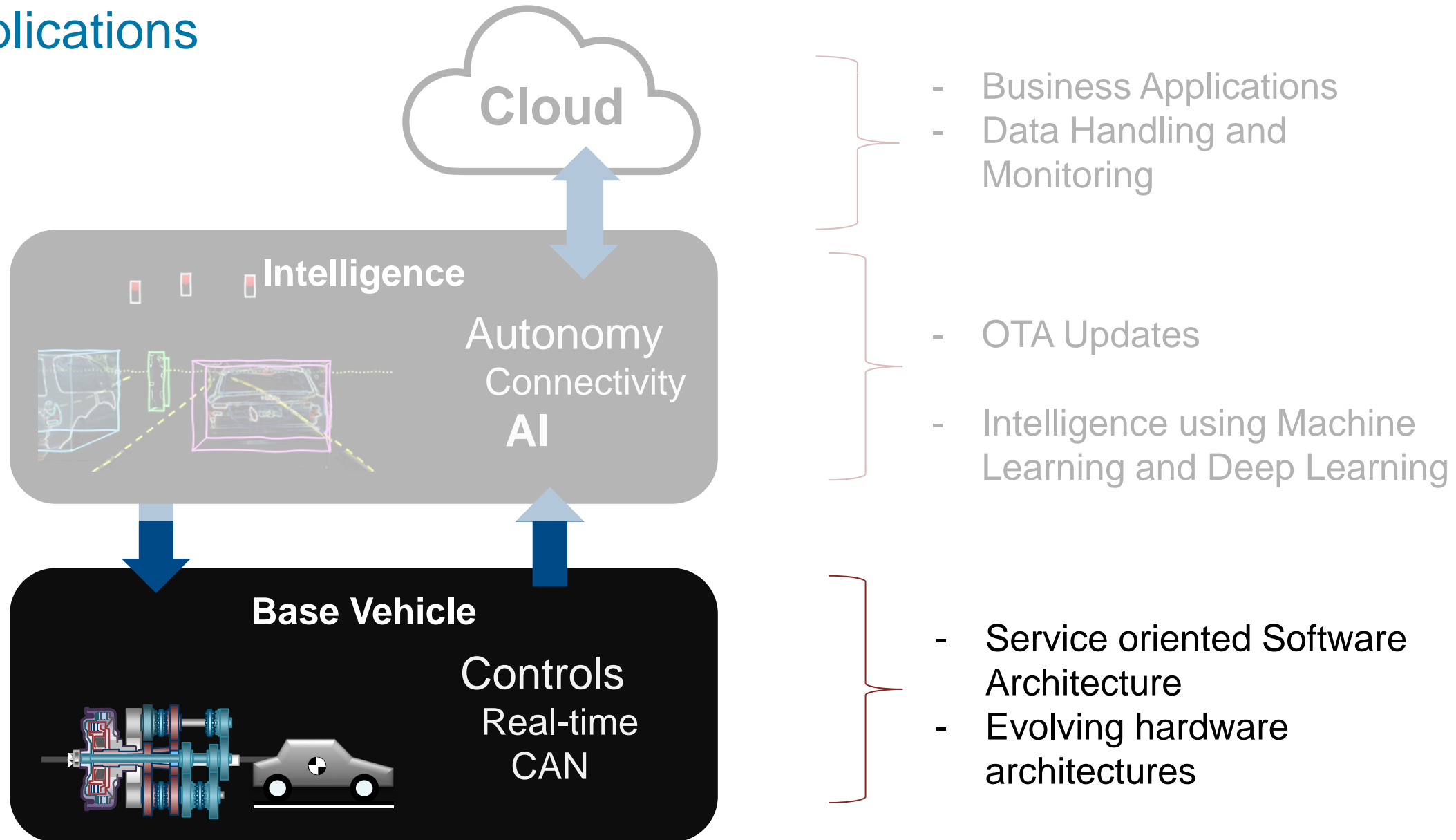
- Build a modular and scalable software platform
- Use the vehicle captured data creatively to re-fine the vehicle design
- Extract data from the vehicle and monetize it for adding extra value to the user
- Over The Air updates of the software – opportunity to provide new features and bug fixes without re-calls



Software-Defined Vehicles: Workflows for In-Car and Cloud Applications



Software-Defined Vehicles: Workflows for In-Car and Cloud Applications

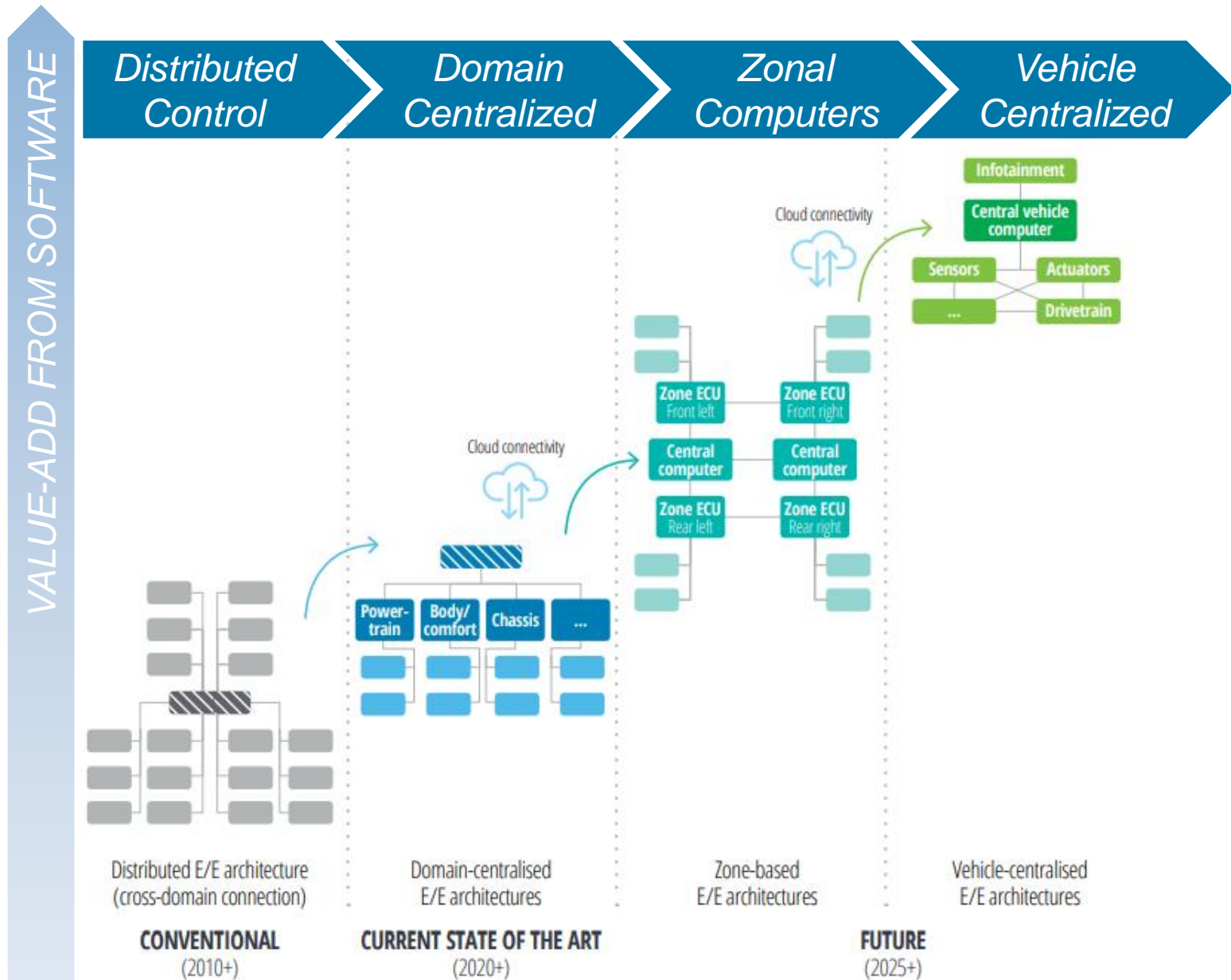


Evolving Architectures

Need to consolidate E&E architectures with rising software complexity

Endgame: One central or few Zone Oriented *domain Independent* controllers

Model, simulate and deploy service-oriented applications



Abstraction and new architectures



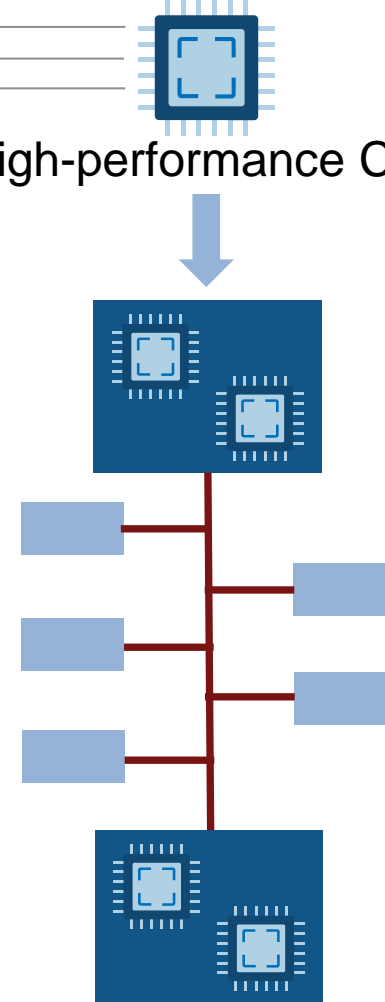
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Exponential growth of SW features

High-performance CPU/GPU

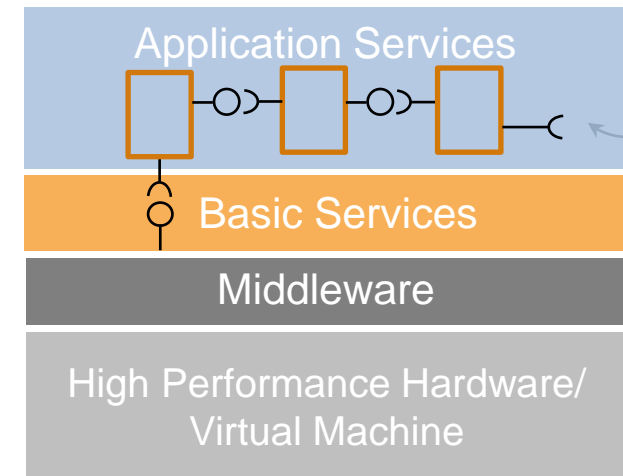


New E/E architectures:
Vehicle and Zone Controllers



SW updates

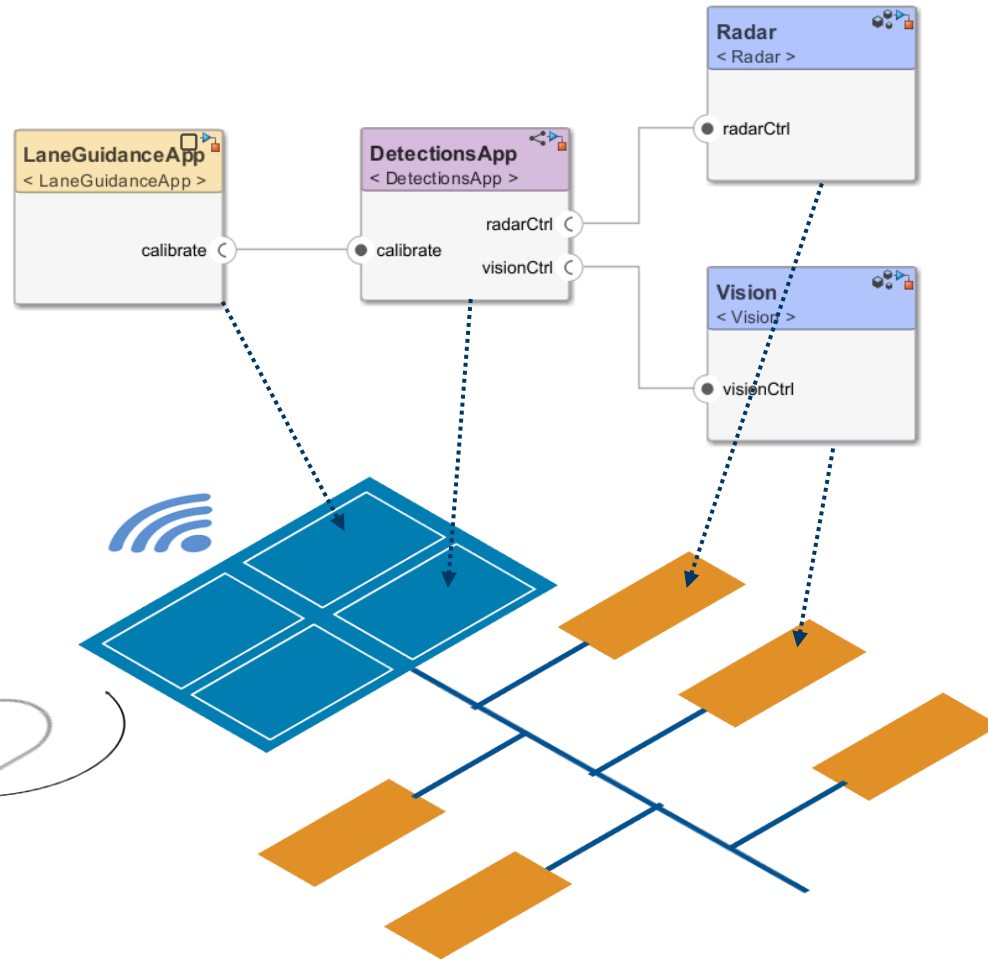
- Frequent
- Selective
- Over-the-air



Higher HW abstraction:
Service-oriented architectures

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Capture execution requirements in a distributed service architecture



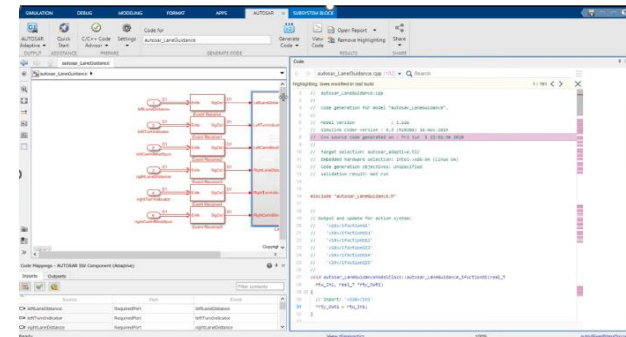
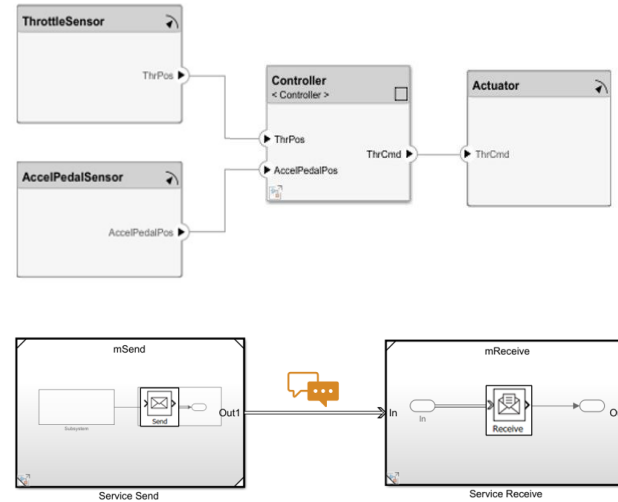
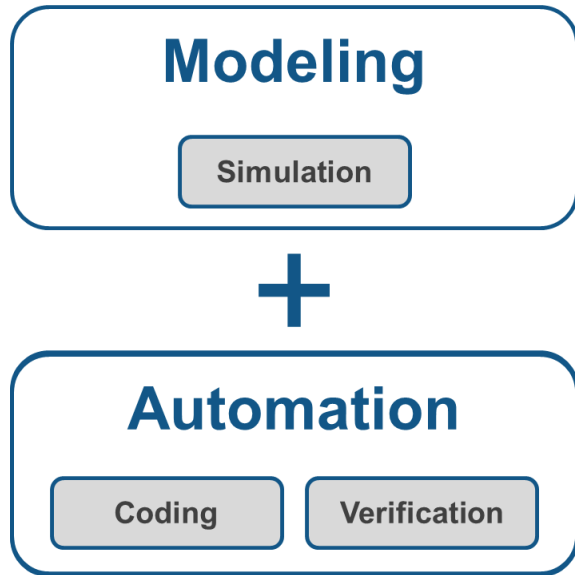
What can I model & simulate in a distributed architecture?

- SOA architectures are event-based
- Describe **periodic, service** and **message** events
- Simulate relative ordering and queueing

Execution Order	Function Name
1	<i>fx</i> LaneGuidanceApp_main
2	☛ DetectionsApp.calibrate.Calibrate
3	☛ Radar.radarCtrl.Adjust
4	☛ Vision.visionCtrl.Adjust
5	☒ DetectionsApp.radarResponse
6	☒ DetectionsApp.visionResponse
7	☒ LaneGuidanceApp.detectionsResponse

Service-oriented architectures (SOA) with Model-Based Design

Simulink is evolving to address the changing architectures



- **Fast design iterations** of service-oriented architectures and applications
- **Maximize reuse** of existing skills and assets
- **Ensure traceability** across all the stages
- **Generate code** compliant to automotive standards
- Deploy to **multiple targets**
- Enable **continuous integration**

AUTOSAR Adaptive in action

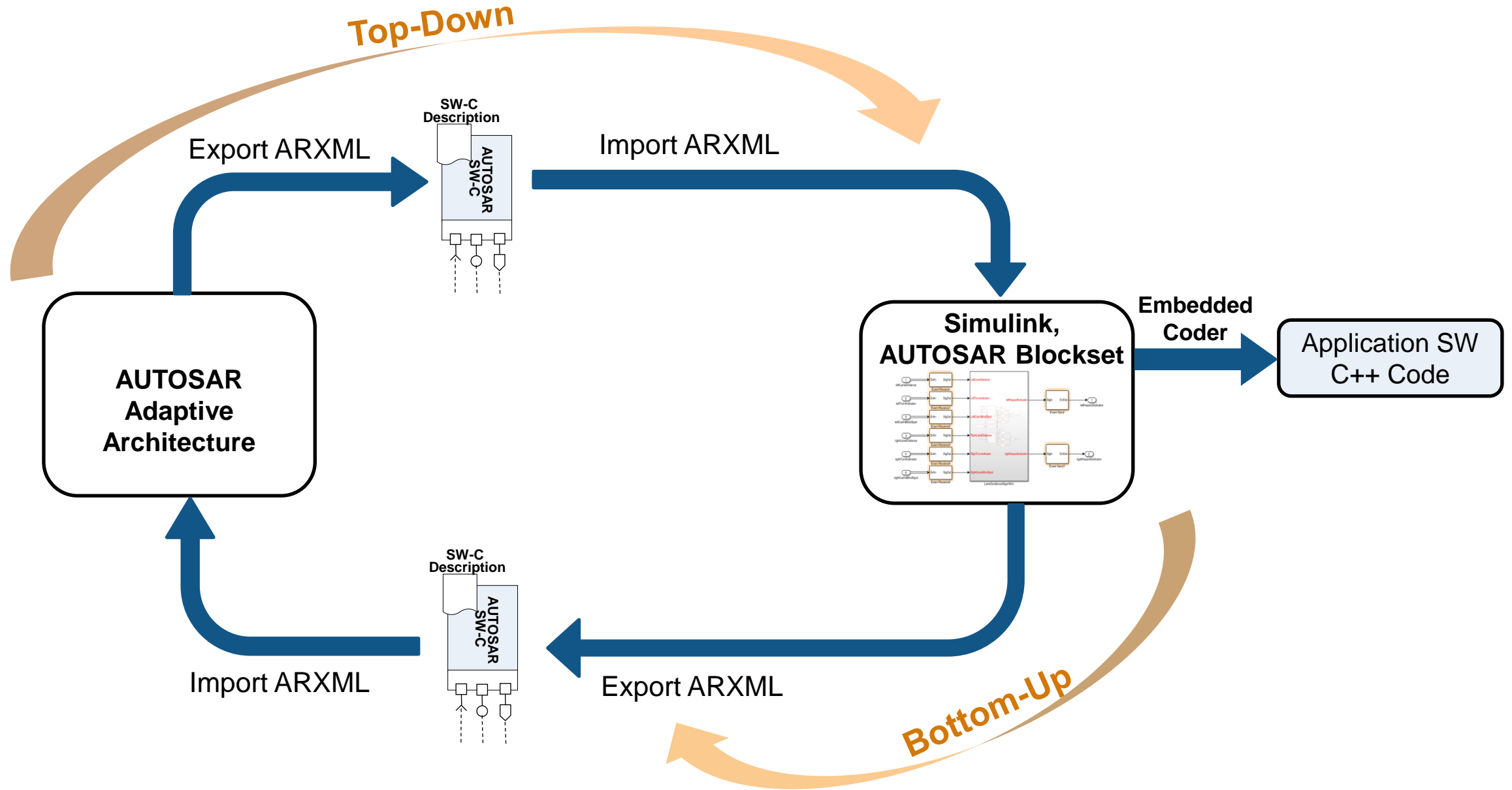
- Create model from ARXML
- Verify AUTOSAR properties
- Configure Service Discovery
- Generate code

The screenshot displays the MathWorks IDE interface for configuring and generating code for an AUTOSAR Adaptive application. Key components visible include:

- Code Editor:** Shows ARXML code for creating a component model:


```
ar = arxml.importer('autosar_LaneGuidance.arxml');
createComponentAsModel(ar, '/LaneGuidance_pkg/LaneGuidance_swc/LaneGuidance');
```
- Configuration Panel:** 'Configuration Parameters: LaneGuidance/Configuration (Active)' shows settings for 'Generate XML file for schema version' (00046 R18-10), 'Maximum SHORT-NAME length' (128), and 'XCP Slave Configuration' (Transport layer: None).
- AUTOSAR Dictionary:** A tree view showing the 'LaneGuidance' package with sub-elements like 'RequiredPorts', 'ProvidedPorts', and 'Service Interfaces'.
- Code Window:** Lists generated files for 'autosar_LaneGuidance.cpp', 'autosar_LaneGuidance.h', and various interface files.
- Manifest Attributes:** A panel for 'RequiredPort' showing 'Instance Identifier' (1) and 'Service Discovery Mode' set to 'DynamicDiscovery'.

AUTOSAR Adaptive workflows



DDS Blockset

Design and simulate DDS applications

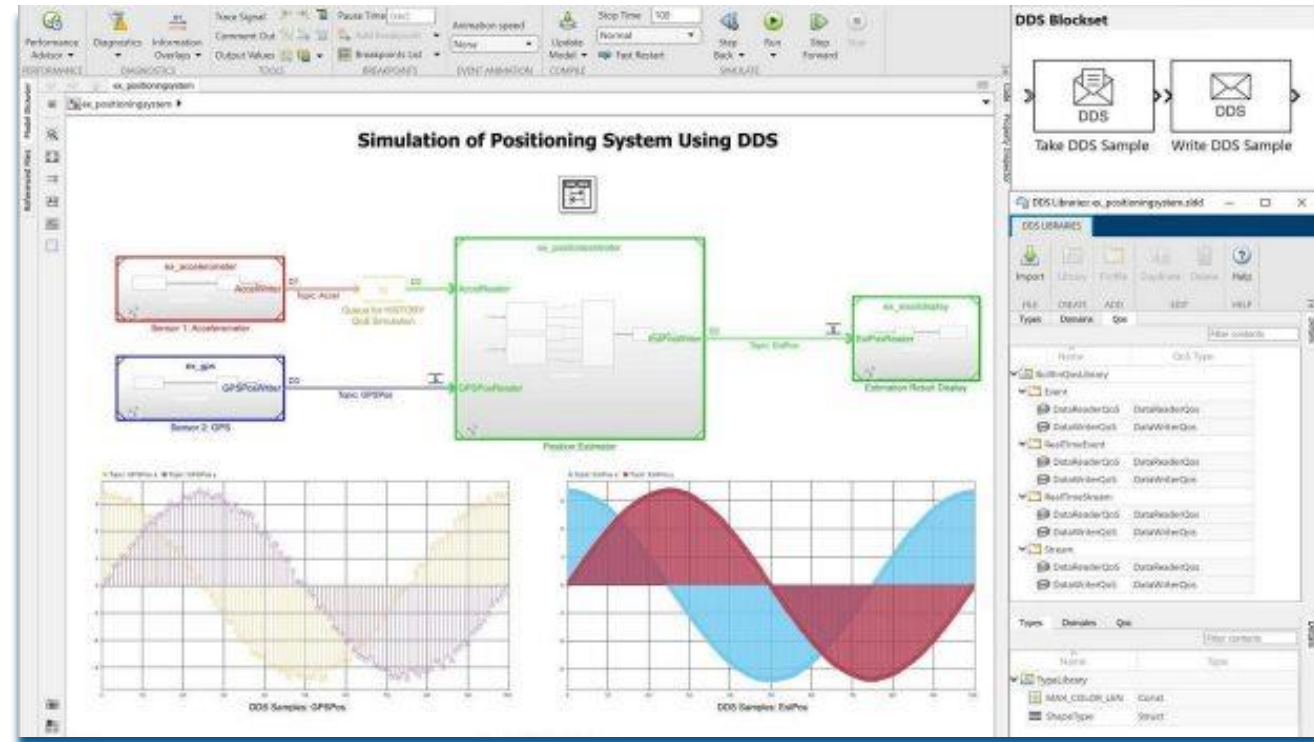
Data Distribution Services (DDS) is a middleware standard uses SOA methodology

Develop software for DDS based embedded systems in Simulink

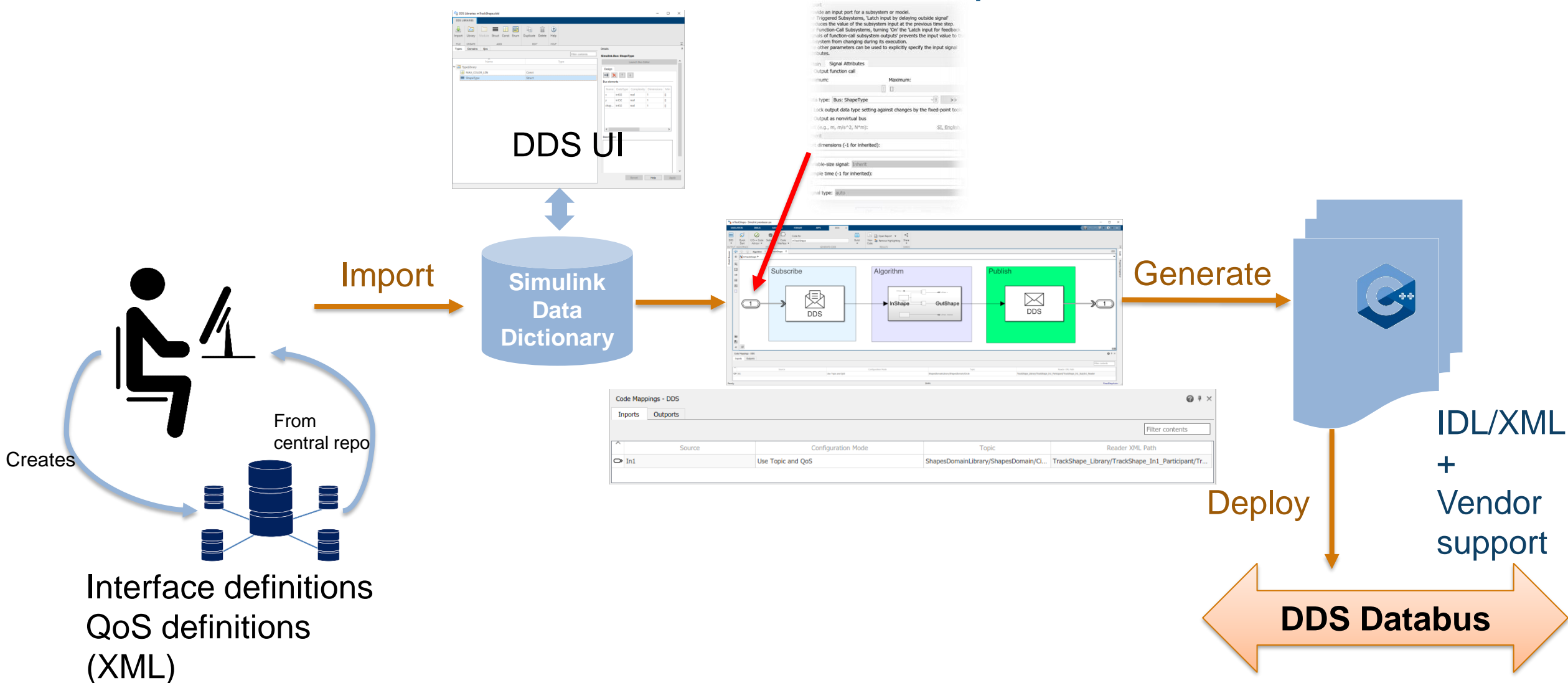
DDS Blockset provides

- Apps and blocks to model and simulate DDS software applications that publish or subscribe to DDS and their QoS
- DDS dictionary to manage DDS definitions
- API's to Import and Export DDS libraries
- C++ production code generation with DDS APIs (with Embedded Coder)

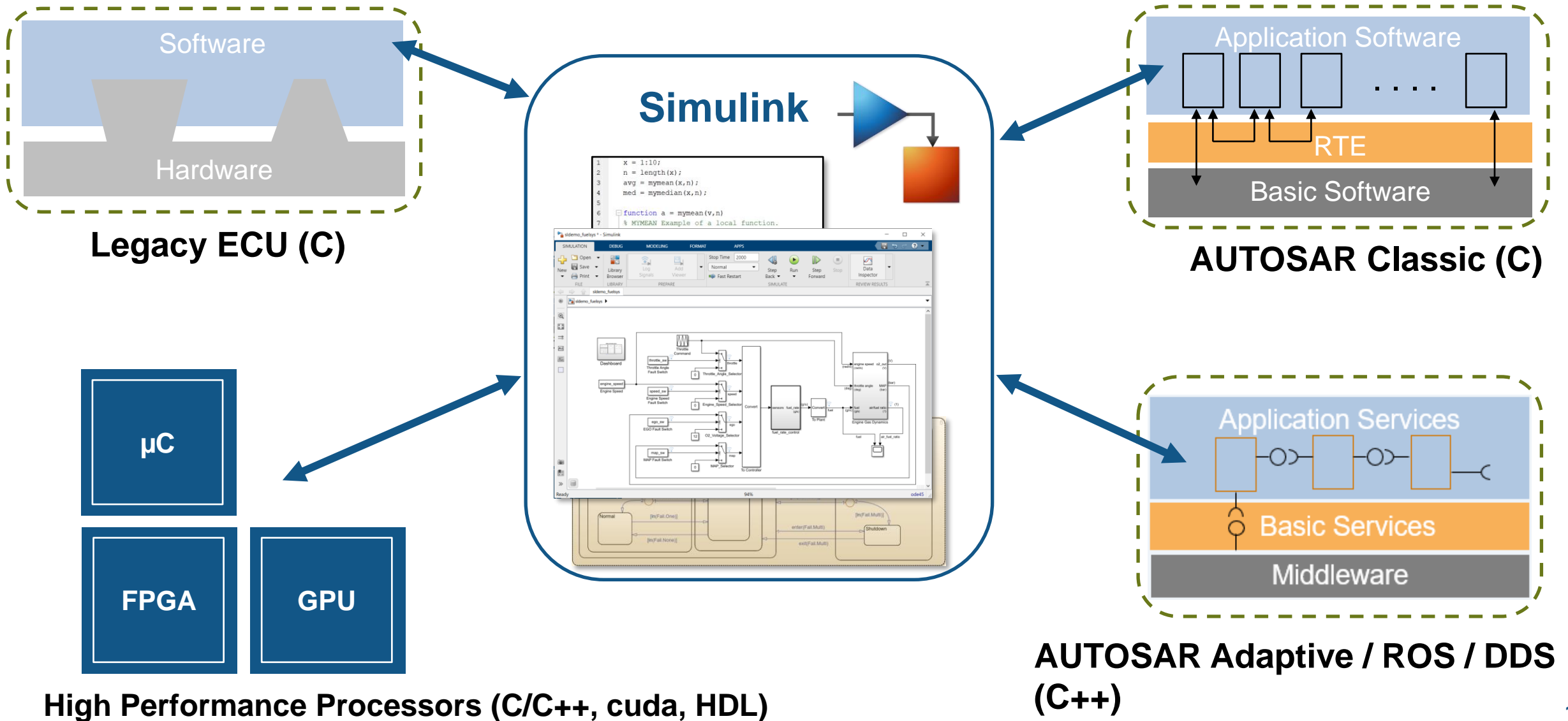
DDS Blockset fully integrates with third-party DDS stacks including RTI Connex and eProsima Fast DDS



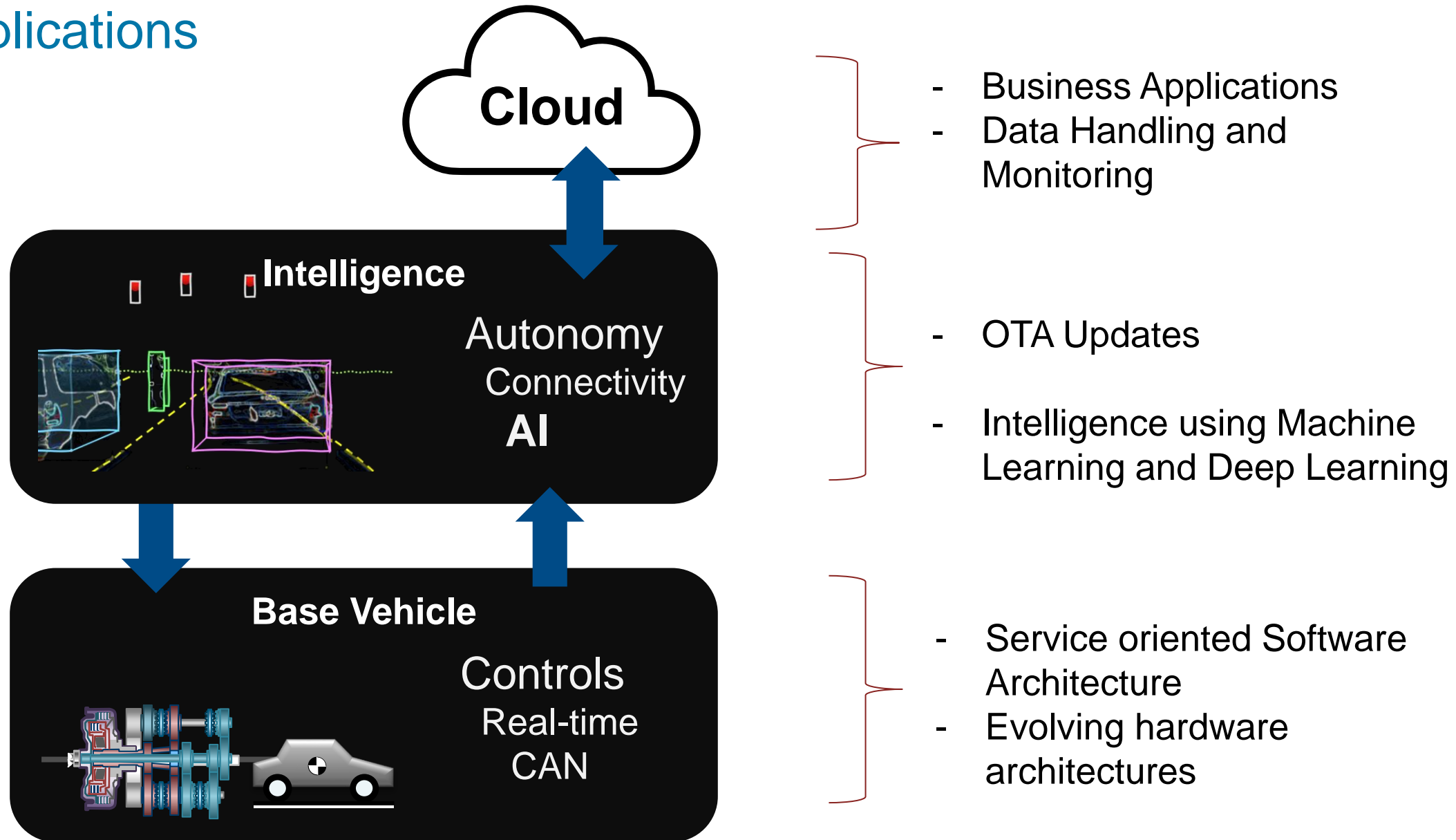
DDS Workflow - User Workflow with UI Steps



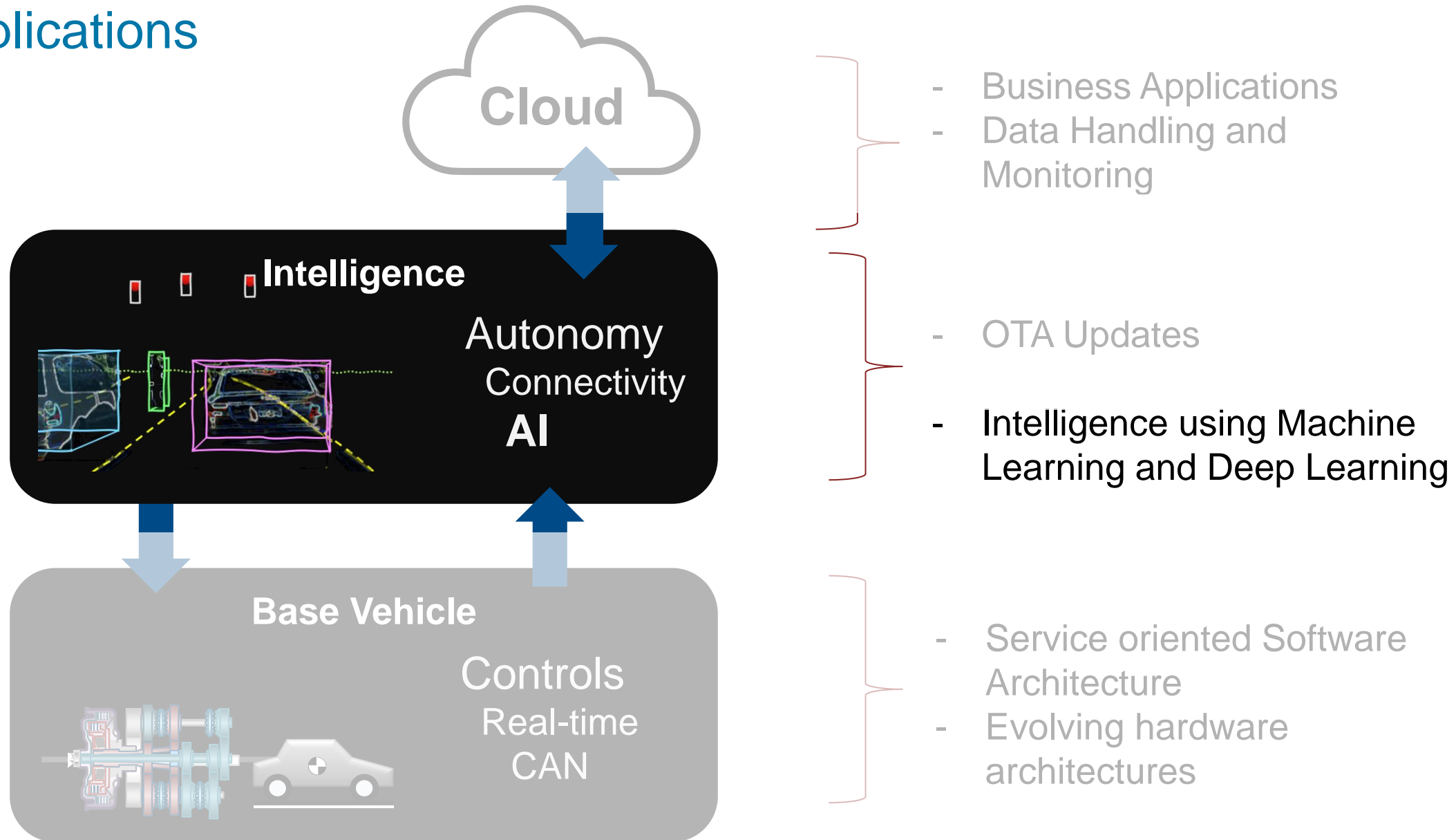
Simulink : design software once, deploy to many targets



Software-Defined Vehicles: Workflows for In-Car and Cloud Applications



Software-Defined Vehicles: Workflows for In-Car and Cloud Applications



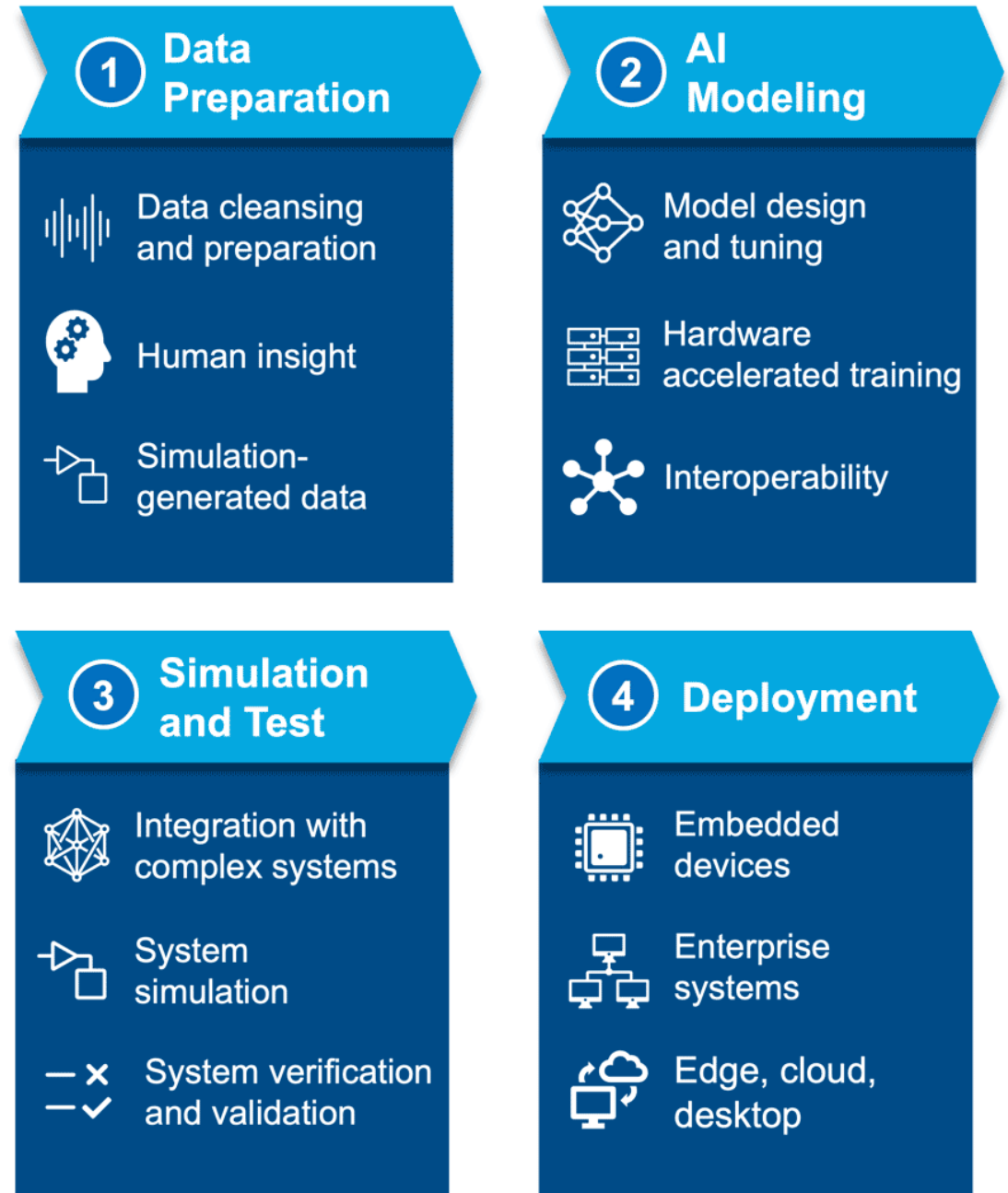
Adding intelligence using Machine Learning and Deep Learning

Software defined vehicles will generate huge amounts of data

Entire workflow for AI

Interoperability with open source

Deployment on various platforms



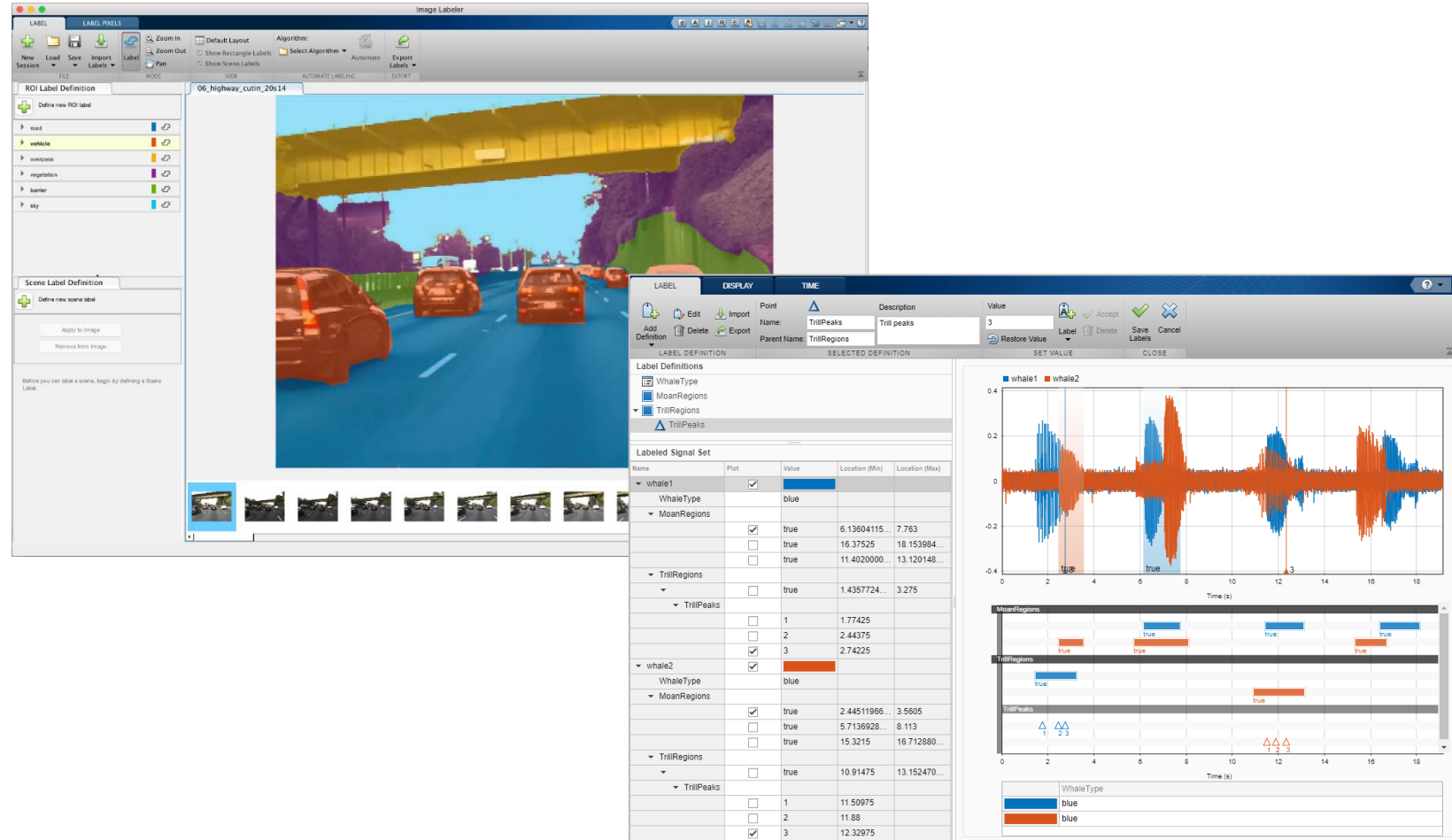
Automated labeling Apps save you weeks to months

1 Data Preparation

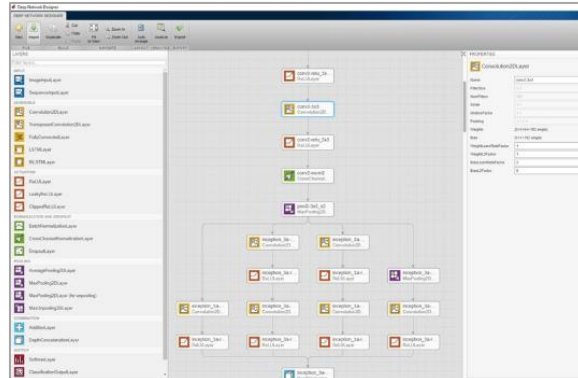
2 AI Modeling

3 Simulation and Test

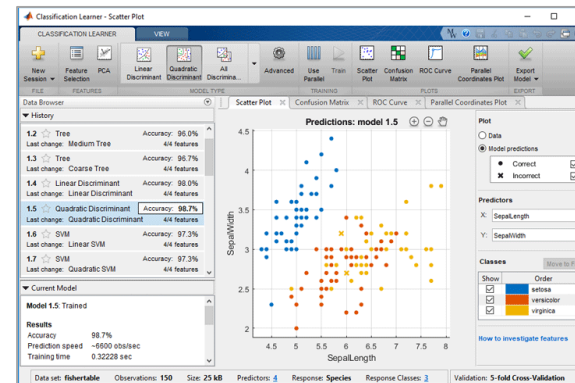
4 Deployment



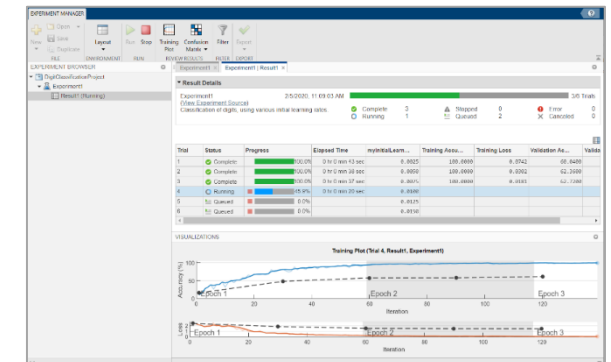
AI modeling Apps automate training, tuning, visualization...



Deep Network Designer app to build, visualize, and edit deep learning networks.



Classification Learner app to try different classifiers and find the best fit for data sets.

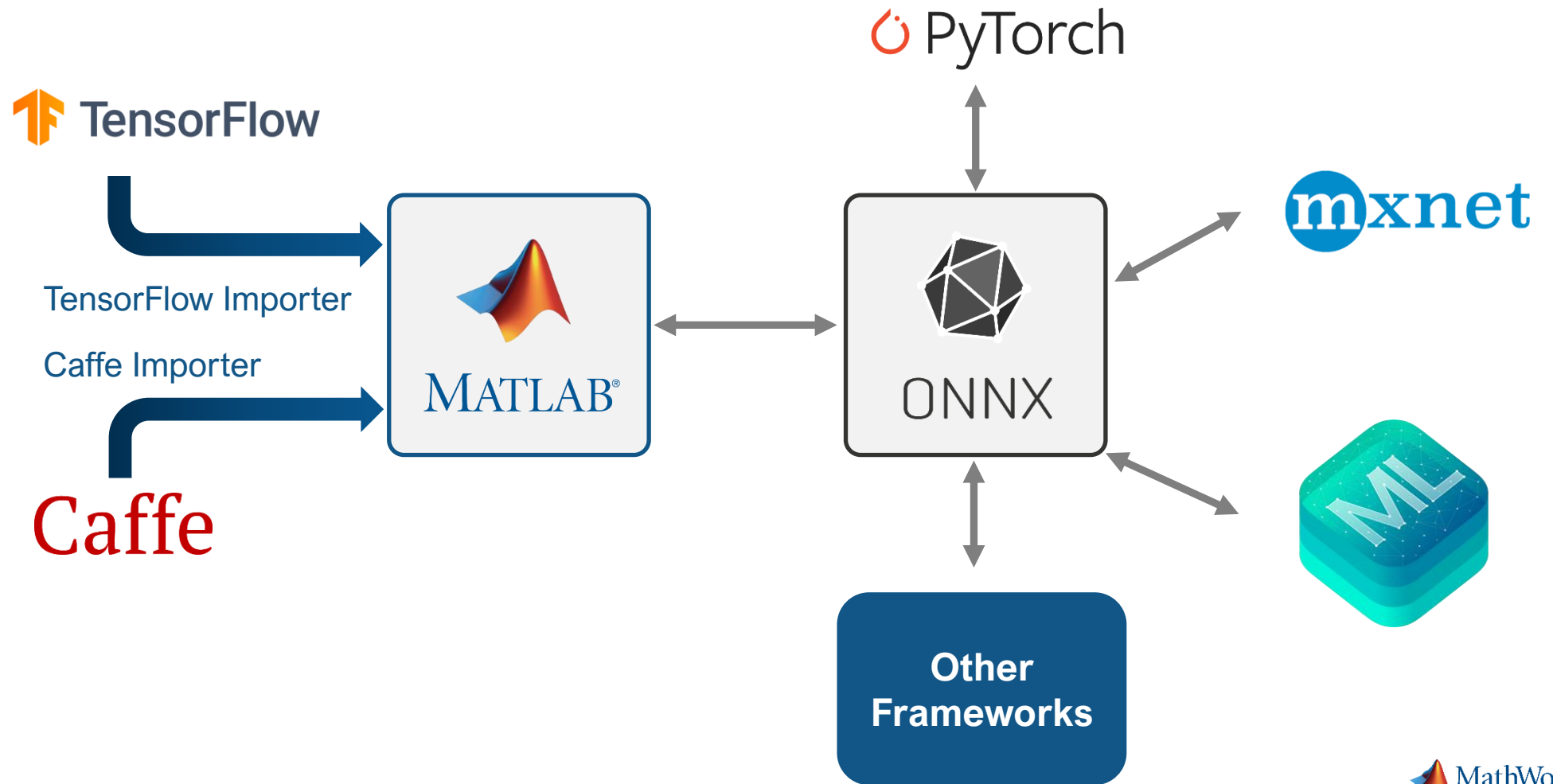


Experiment Manager app to run deep learning experiments to train networks and compare results.

- 1 Data Preparation
- 2 AI Modeling
- 3 Simulation and Test
- 4 Deployment

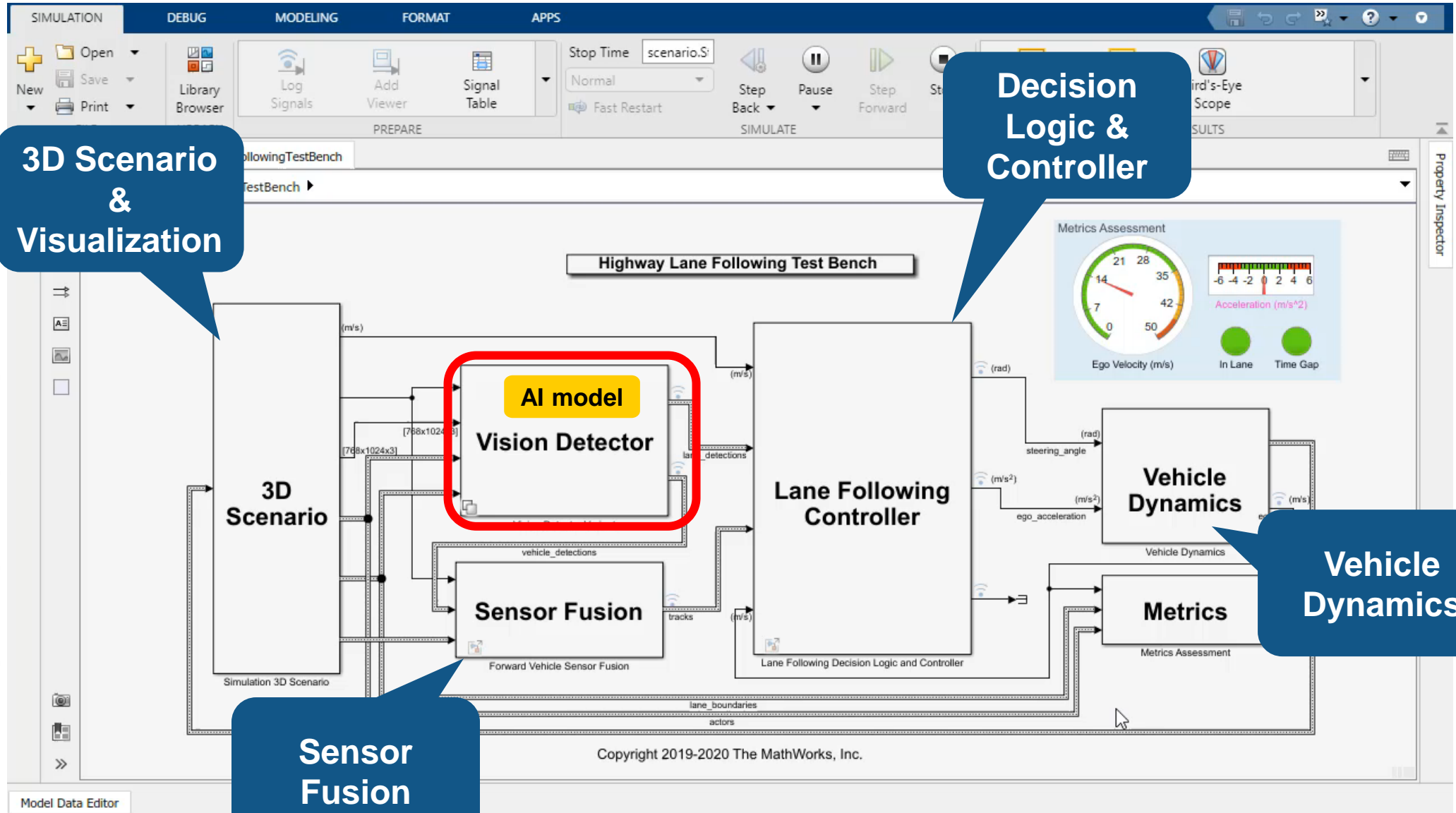
Access AI models from the broader AI community

- 1 Data Preparation
- 2 AI Modeling
- 3 Simulation and Test
- 4 Deployment

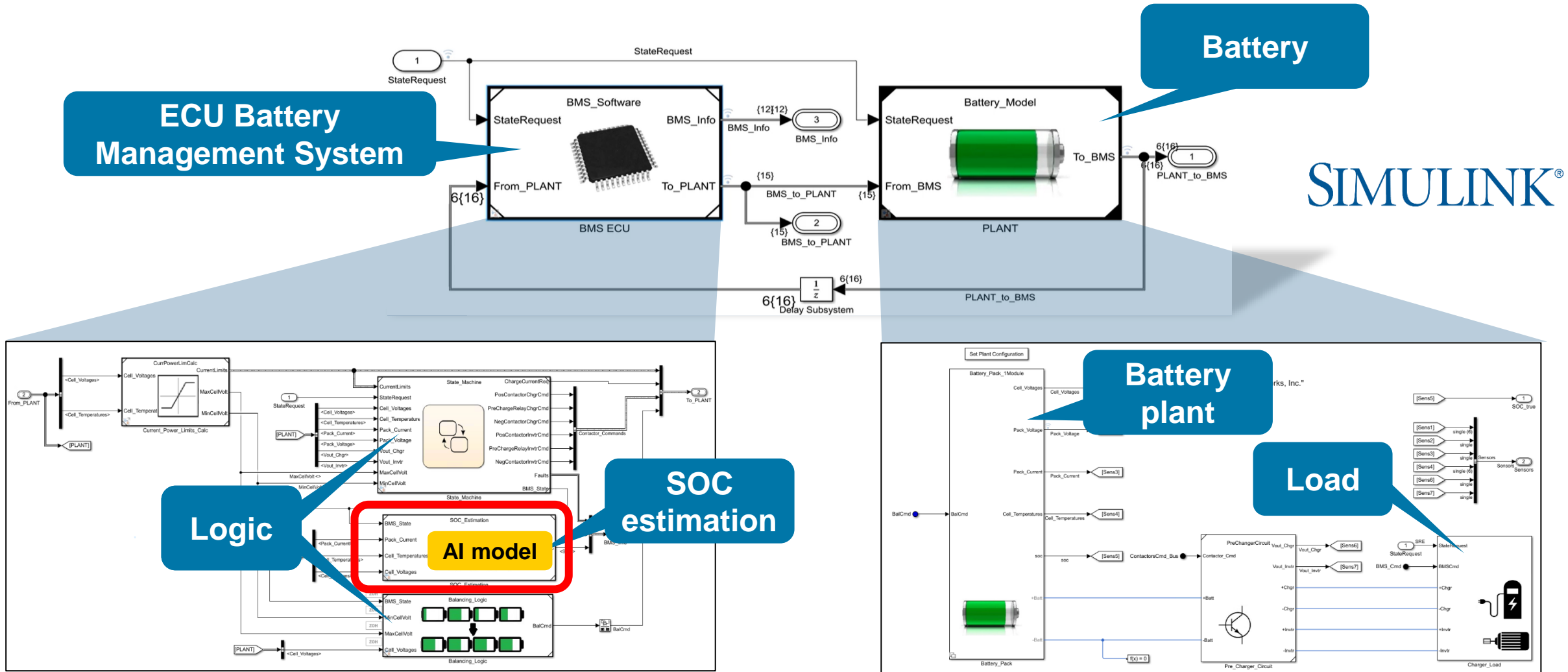


AI for Vision Detection

- 1 Data Preparation
- 2 AI Modeling
- 3 Simulation and Test
- 4 Deployment



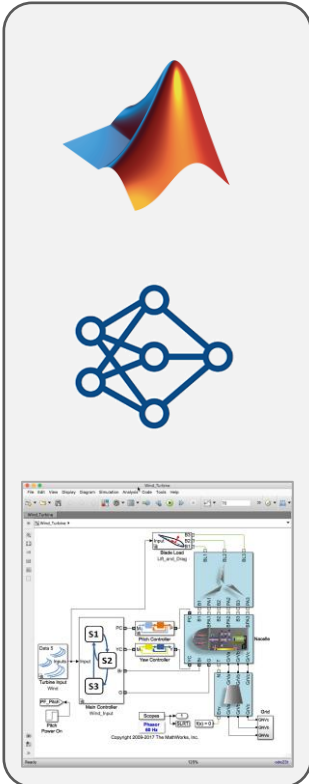
AI for Battery State of Charge (SOC) Estimation



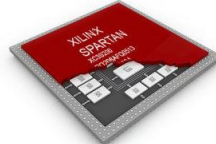
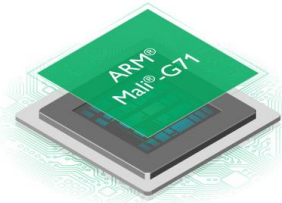
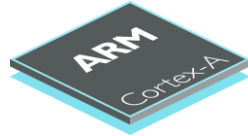
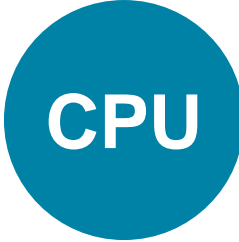
Closed-loop system

Deploy to any processor with zero coding errors

- 1 Data Preparation
- 2 AI Modeling
- 3 Simulation and Test
- 4 Deployment

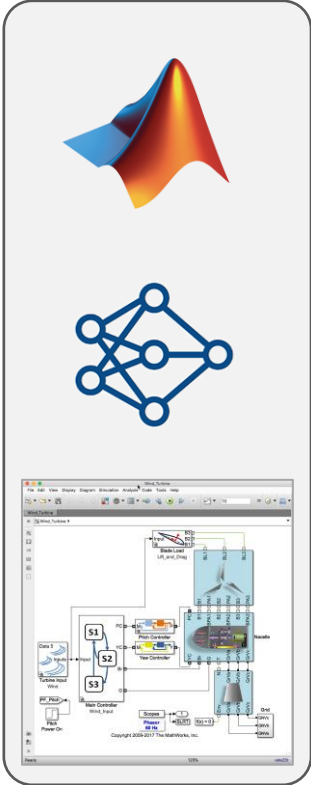


Code Generation

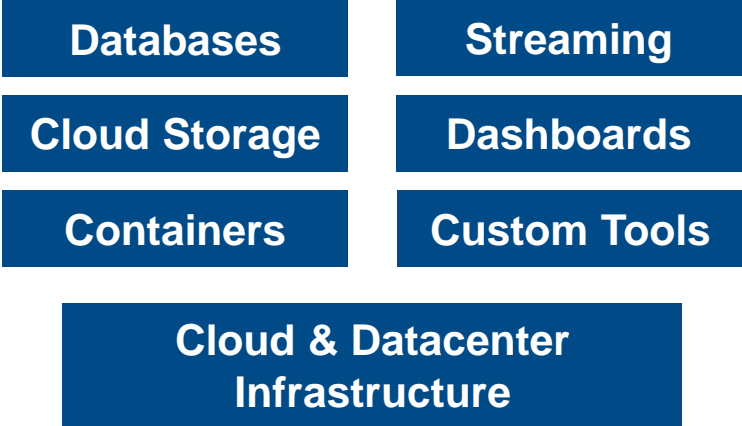
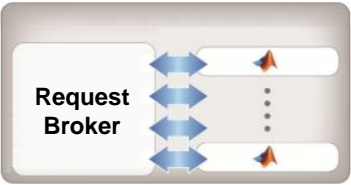


Deploy to any enterprise IT infrastructure

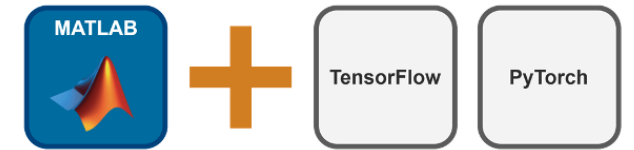
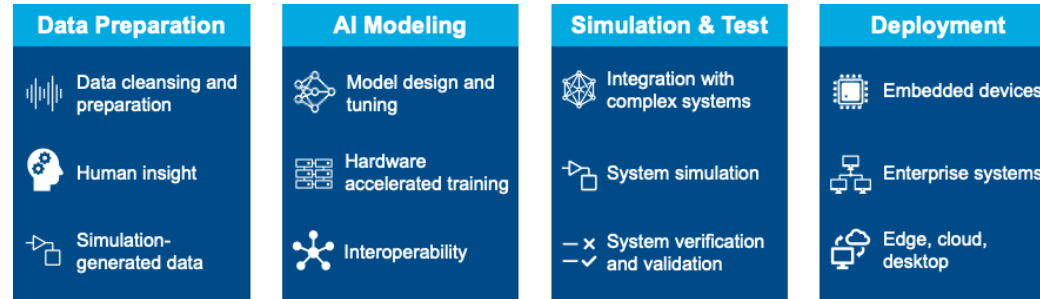
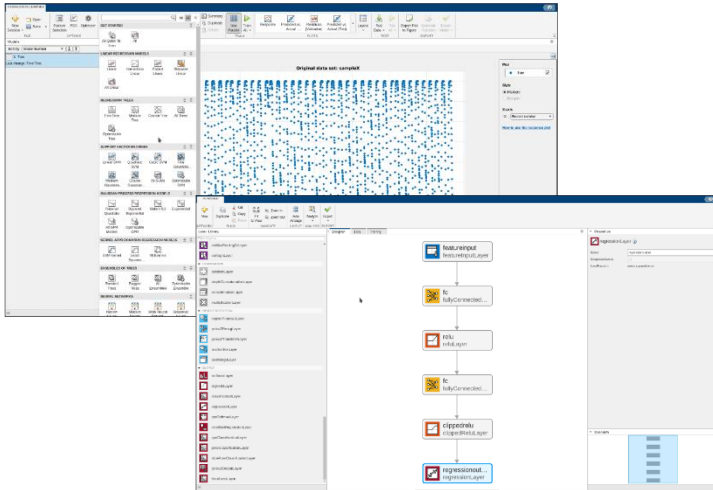
- 1 Data Preparation
- 2 AI Modeling
- 3 Simulation and Test
- 4 Deployment



MATLAB Production Server



AI using Machine Learning and Deep Learning

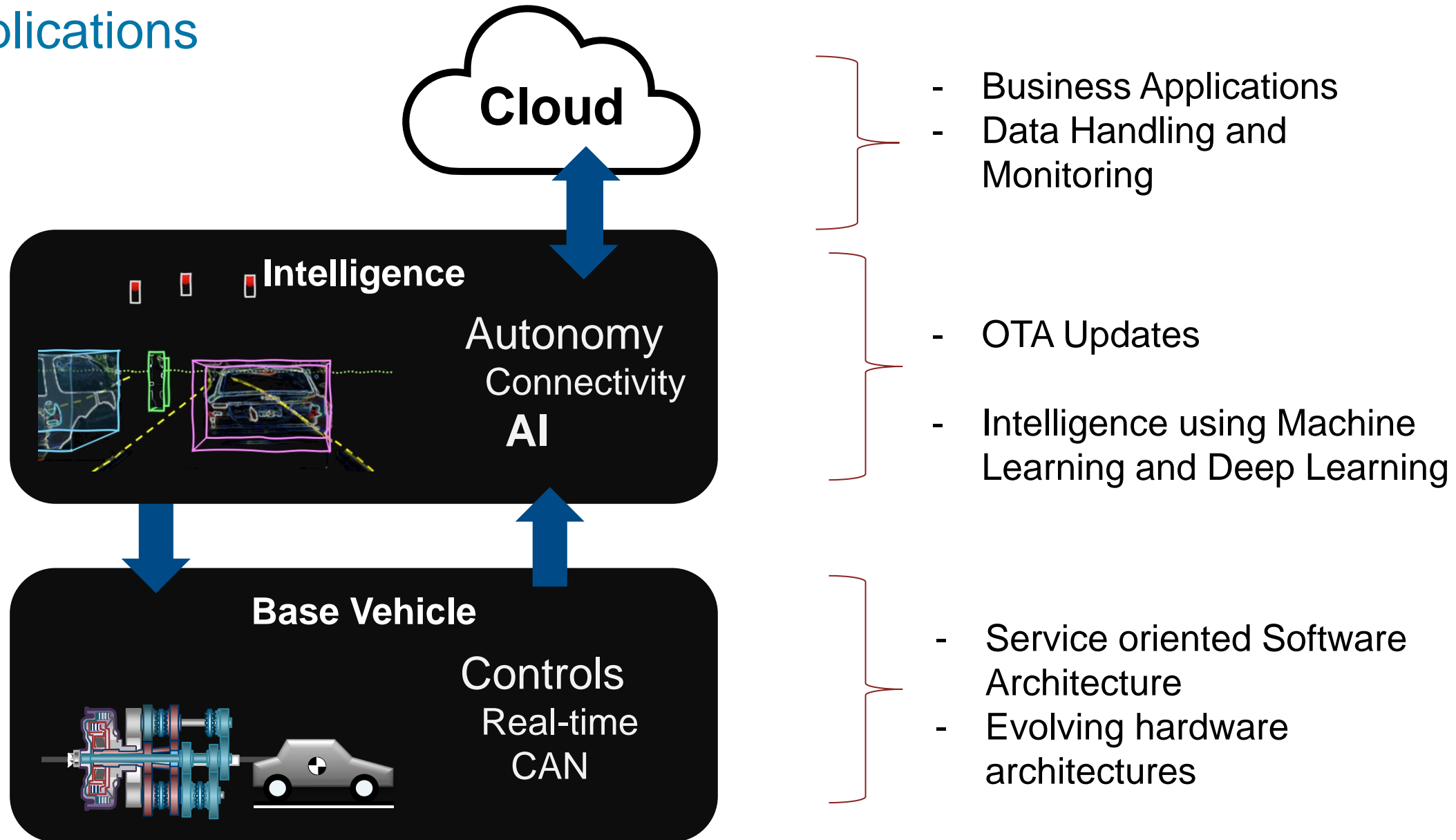


Low-Code Tools to Get Started

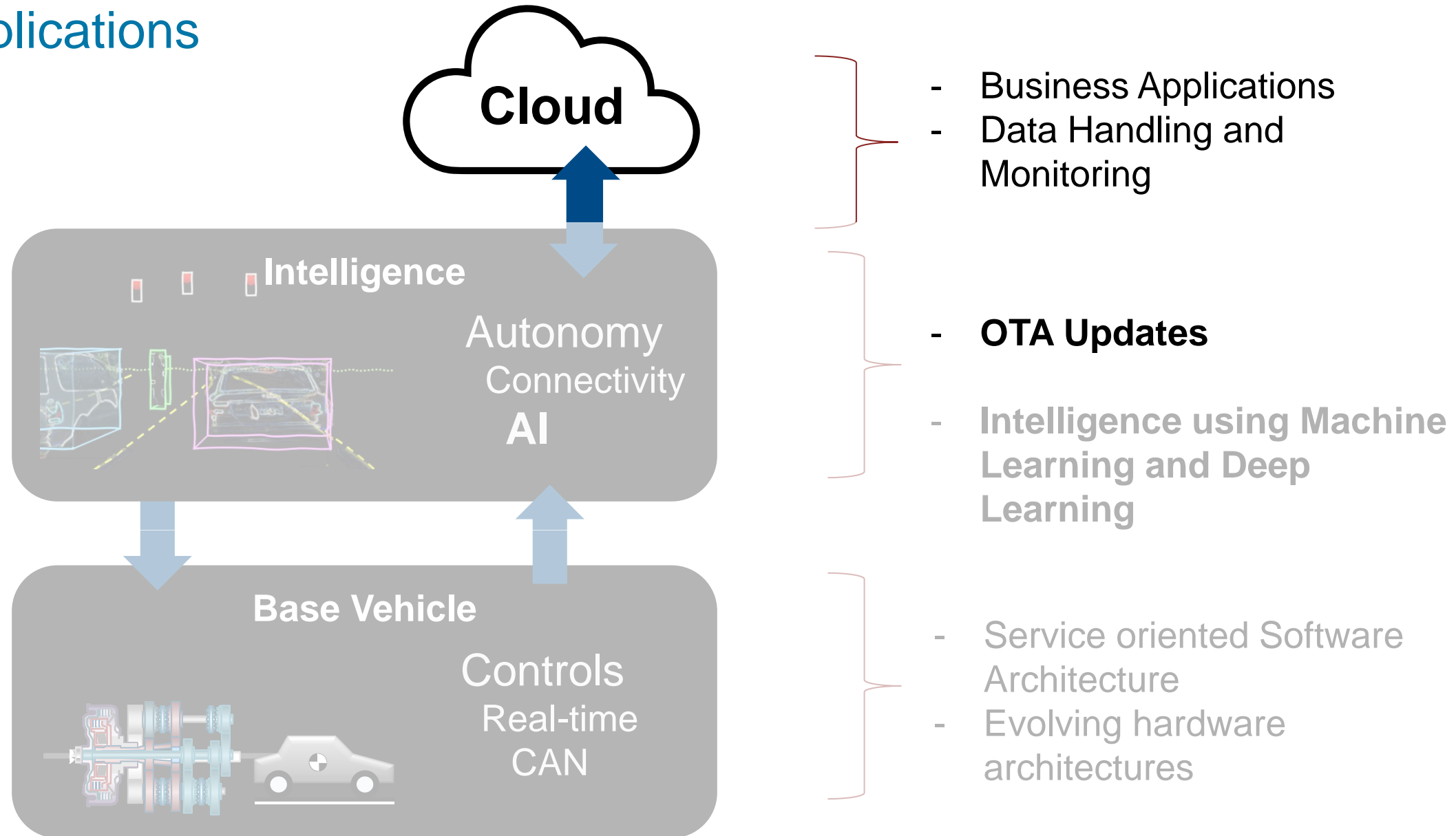
Complete Workflow from Data to Deployment

Exchange Models with Other Frameworks

Software-Defined Vehicles: Workflows for In-Car and Cloud Applications



Software-Defined Vehicles: Workflows for In-Car and Cloud Applications



Cloud Workflows



Develop
using online tools

Make deployment of software tools simple

Give engineers access to their tools from anywhere



Connect to data & simulate
using elastic resources

Access to more data and compute resources

Make design robust with limitless real-world scenarios



Integrate & test
using cloud-based CI

Use latest tooling and compute resources

Allow whole engineering team to join early integration



Deploy
software and simulation

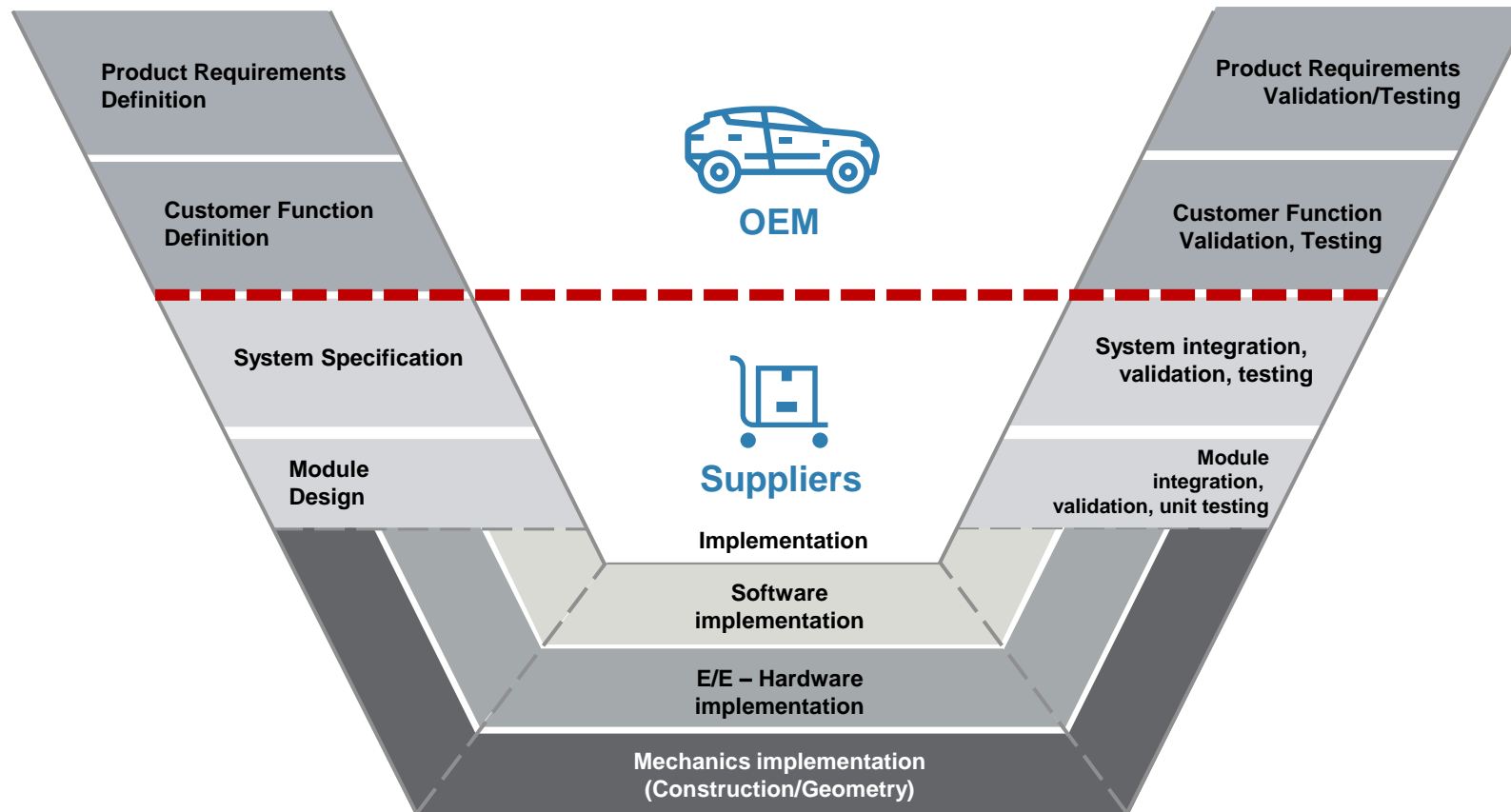
Extend deployment to a new platform

Create new businesses with live update and digital twin

<p>Cloud Native Connectors</p>	<p>Coding Tools & Services</p> 	<p>Data Access</p> 	<p>Coding & Data Science Platforms</p> 	<p>Containers</p> 	<p>Public Clouds</p> 
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What can we learn from the 'V-Model' for the future?

Vehicle Development Process



Model-Based Systems Engineering

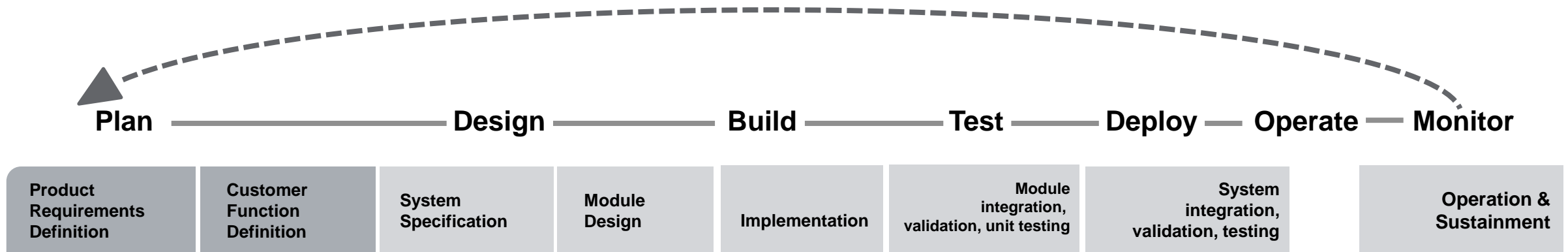
For years the 'V' model driven Vehicle Development Process has served the industry well.

This strong V-model oriented approach has resulted in issues for **software development** process.

Some impacts:

1. Missing a milestone meant that the feature will not make it into the series vehicle.
2. Big bang integration was expected to just work
3. There was no room for failure and the cost of failure has been very high ('zero-defect' quality principle)
4. Missing understanding of full vehicle system in module teams, which leads to integration issues and calls backs.

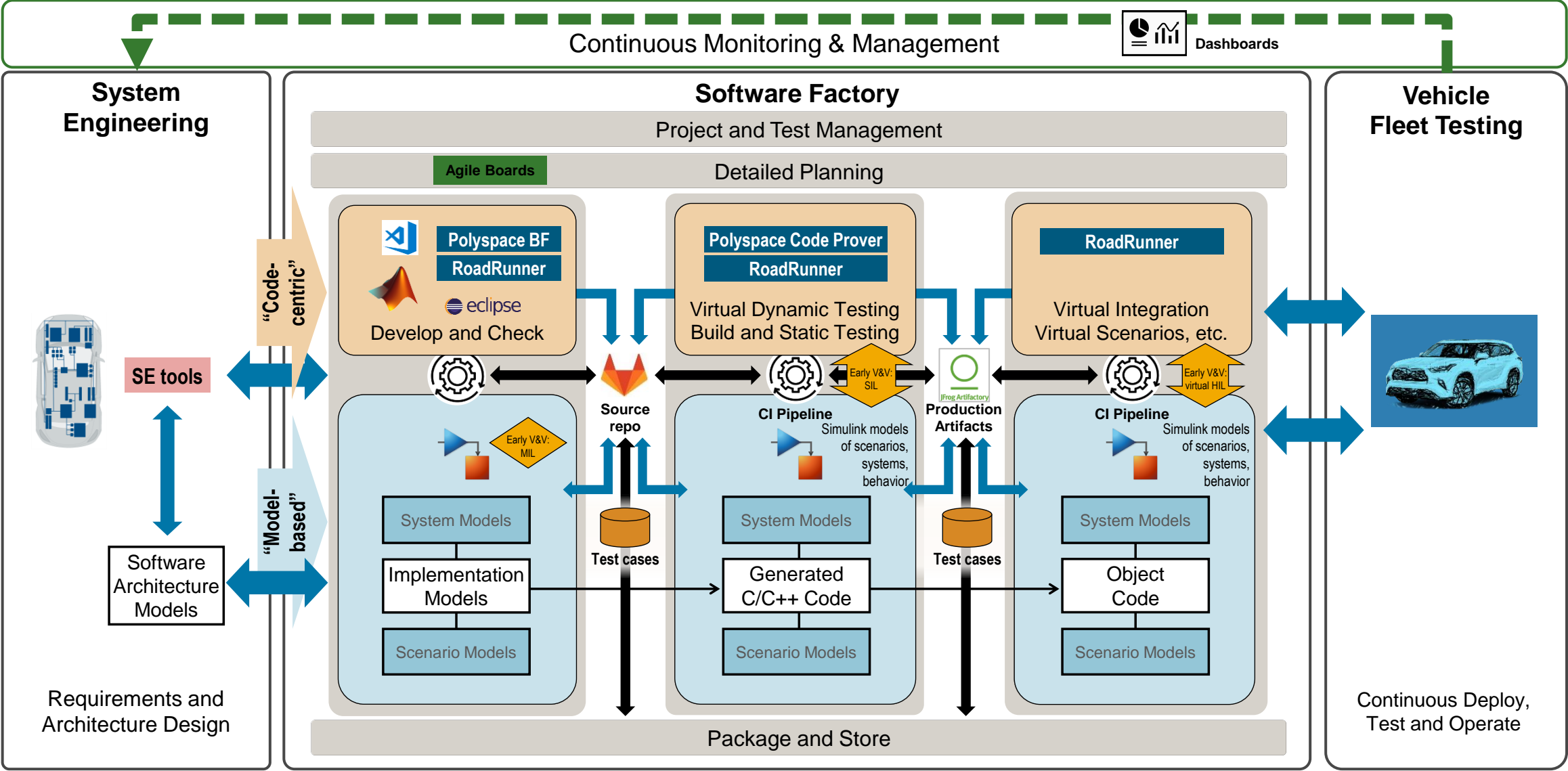
An Automotive View of the DevOps Lifecycle



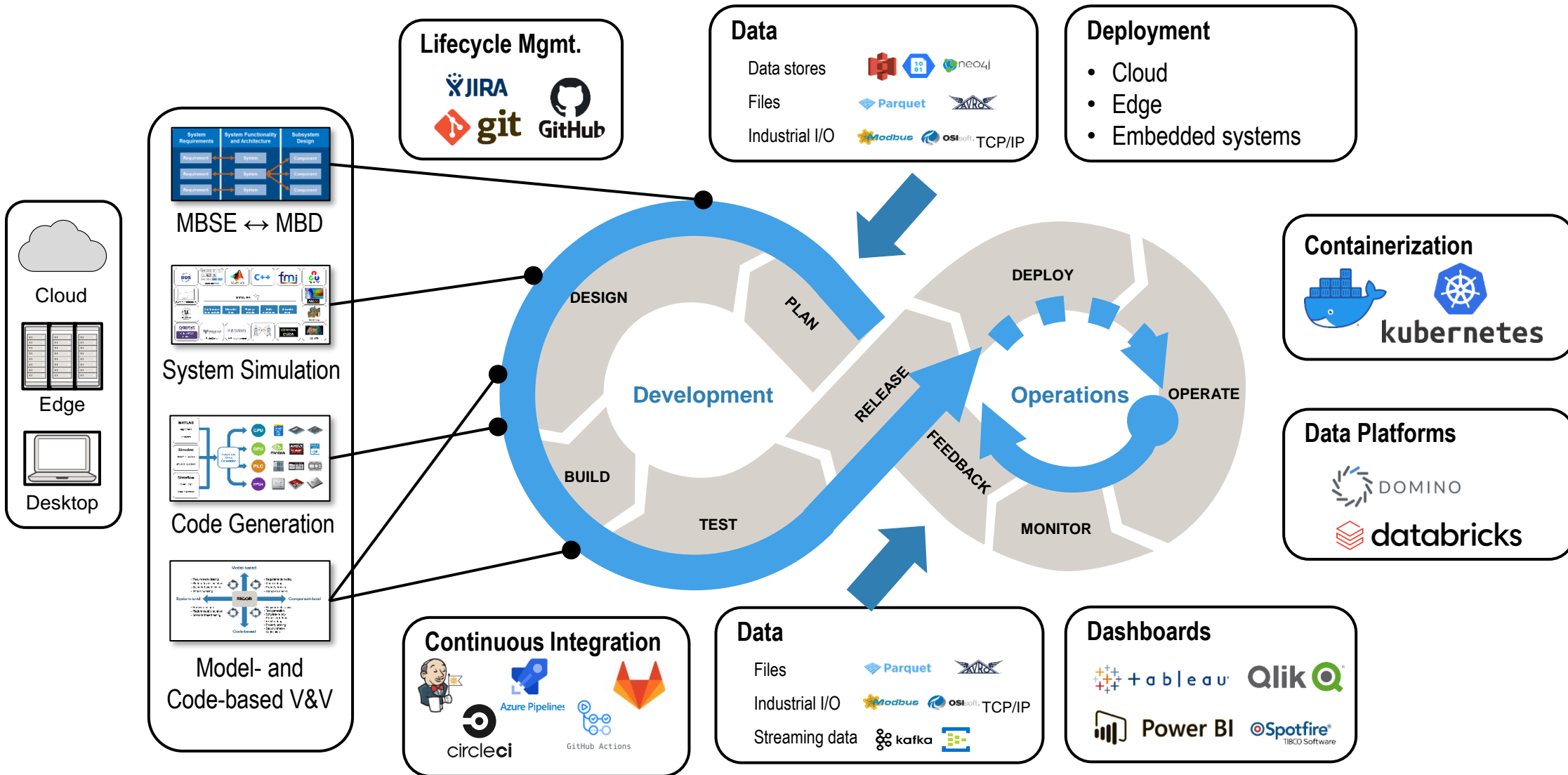
Perpetually Upgradeable Vehicles

- Faster Development and Release Cycles
- Better Leverage Data from System Operation
- Enable New Types of Algorithms and Functionality in the Field

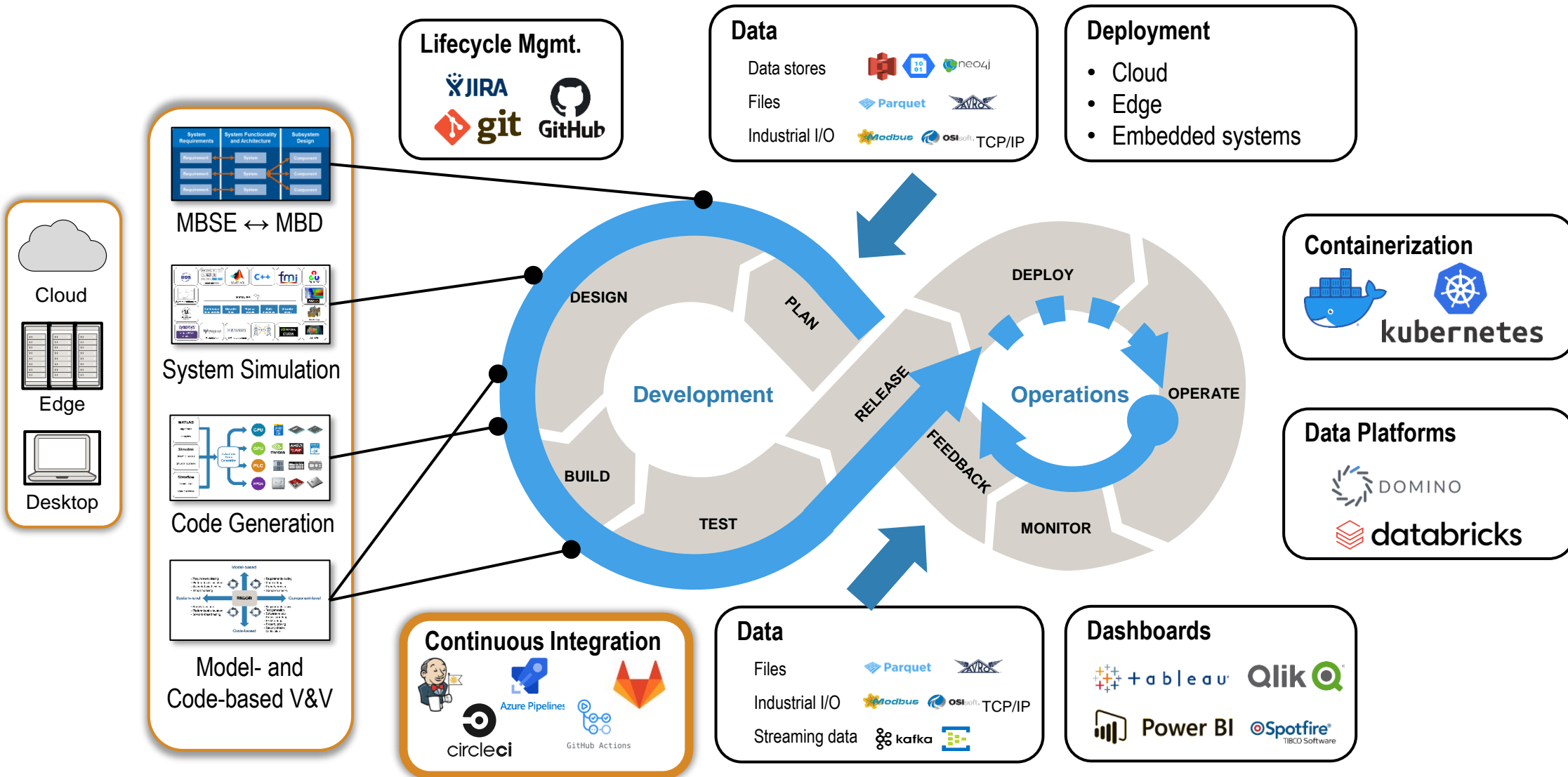
Integrating Model-Based Design in Software Factory



Example for DevOps building blocks for embedded production SW



Continuous Integration for embedded production SW



Continuous Integration Workflow with MATLAB and Simulink



Source Control Server



CI Server

Develop

Test

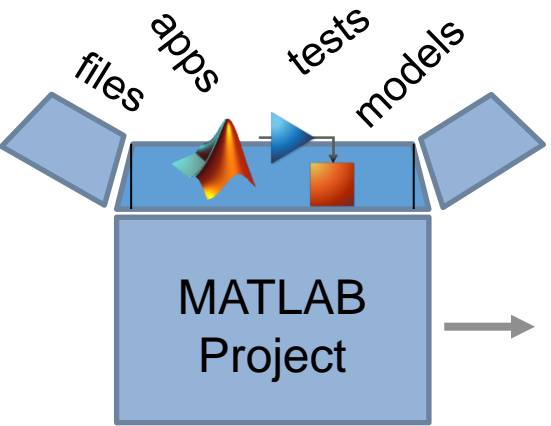
Build

Notify and Deploy

- Run tests:
 - ✓ MATLAB Unit Tests
 - ✓ Simulink Test

- Compile MEX
- Generate Code
- Package (Toolboxes, Apps)

- Publish reports
- Email Notification
- Publish to Server
- Hardware



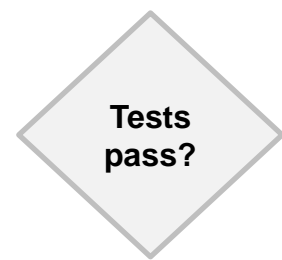
Commit and push changes to Git



GitLab triggers Jenkins

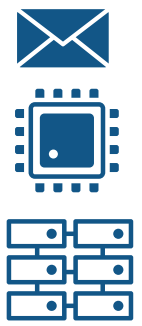


Jenkins run tests



Java
MATLAB
C/C++
Python

Build, generate code and package



Continuous Integration (CI) is a software development practice that involves several steps



- Git
- GitHub
- Subversion
- GitLab
-
-

- Push
- Merge Request
- Pull Request
- Check In
- Periodic
- Manual

- Run MATLAB / Simulink Tests
- Run Performance Tests
- Compile MEX Files
- Generate Code†
- Package Toolboxes
- Build Components with MATLAB Compiler Stack†
- Integrate with other Software Technologies

- Publish:
 - Test Results
 - Coverage Results
 - Performance Results
- Accept Merge Request
- Email Notification
- Build Another Project

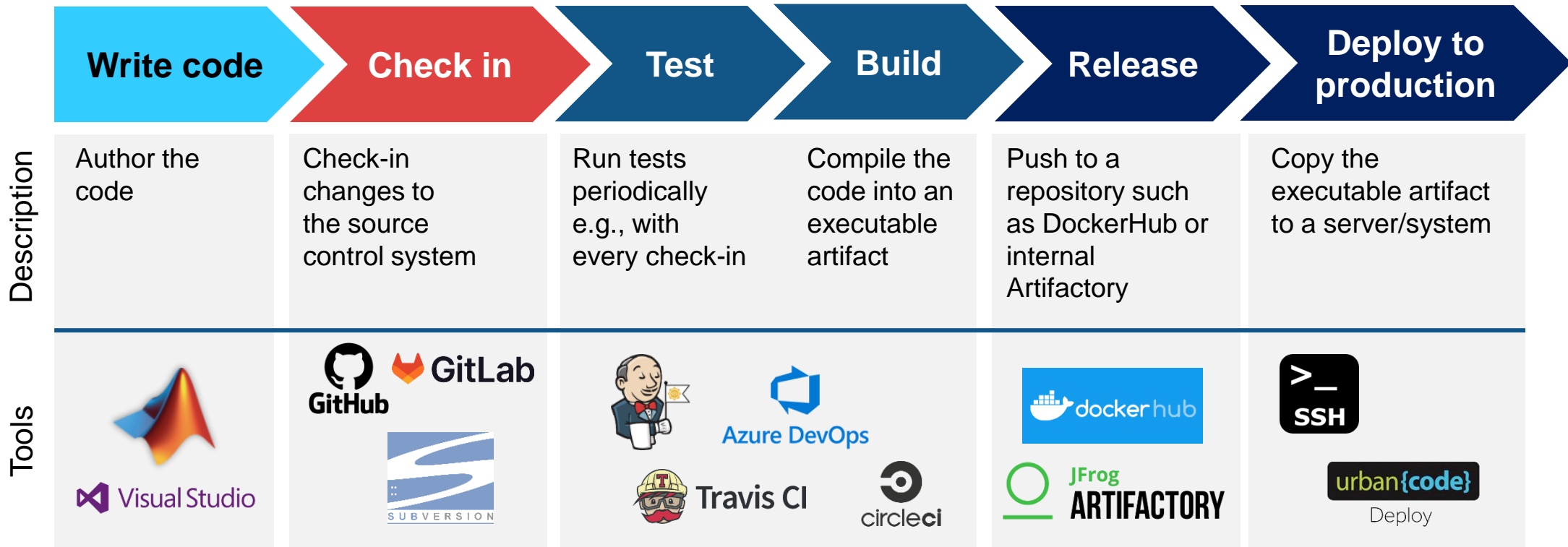
† Transformation products (e.g., MathWorks Coder and Compiler products) may require Client Access Licensing (CAL)

Continuous Delivery and Deployment (CD)

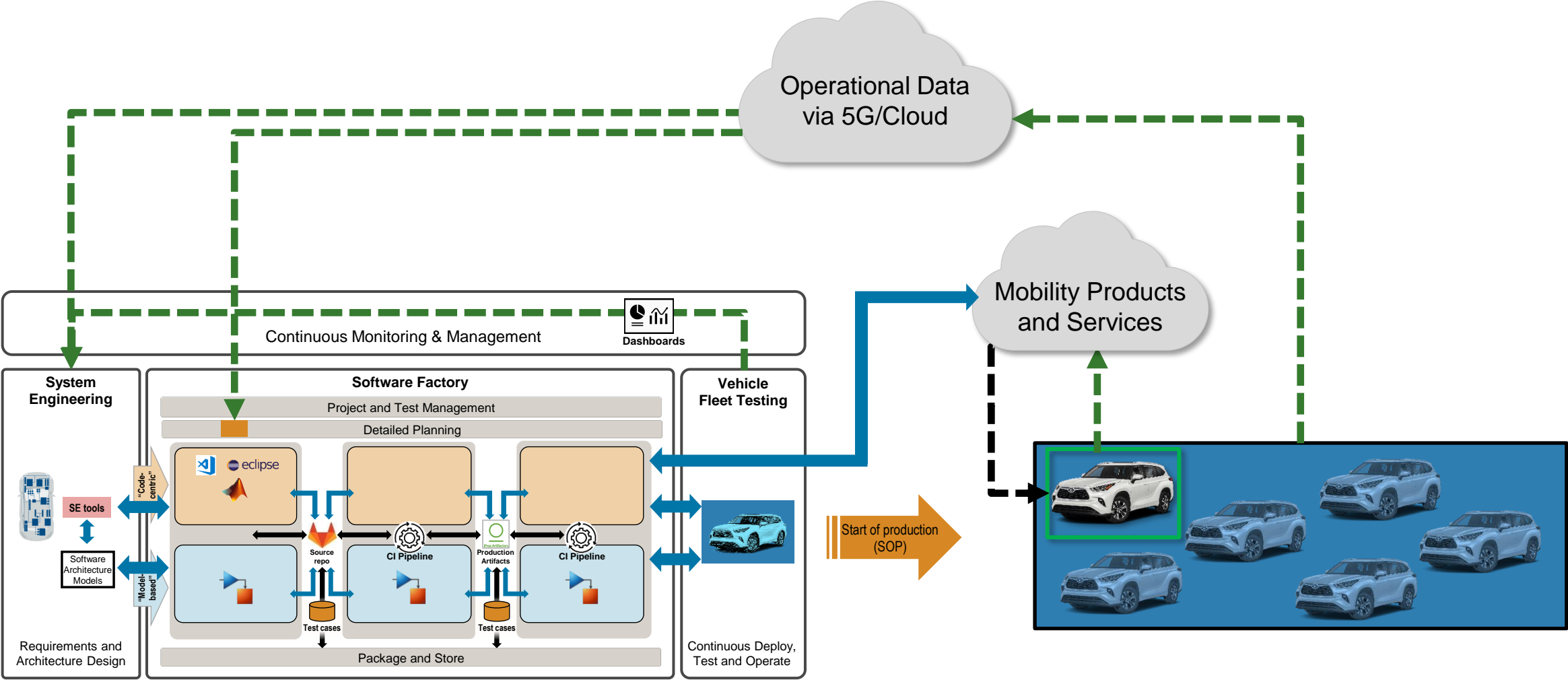
CI =
Continuous
Integration

CD =
Continuous
Delivery

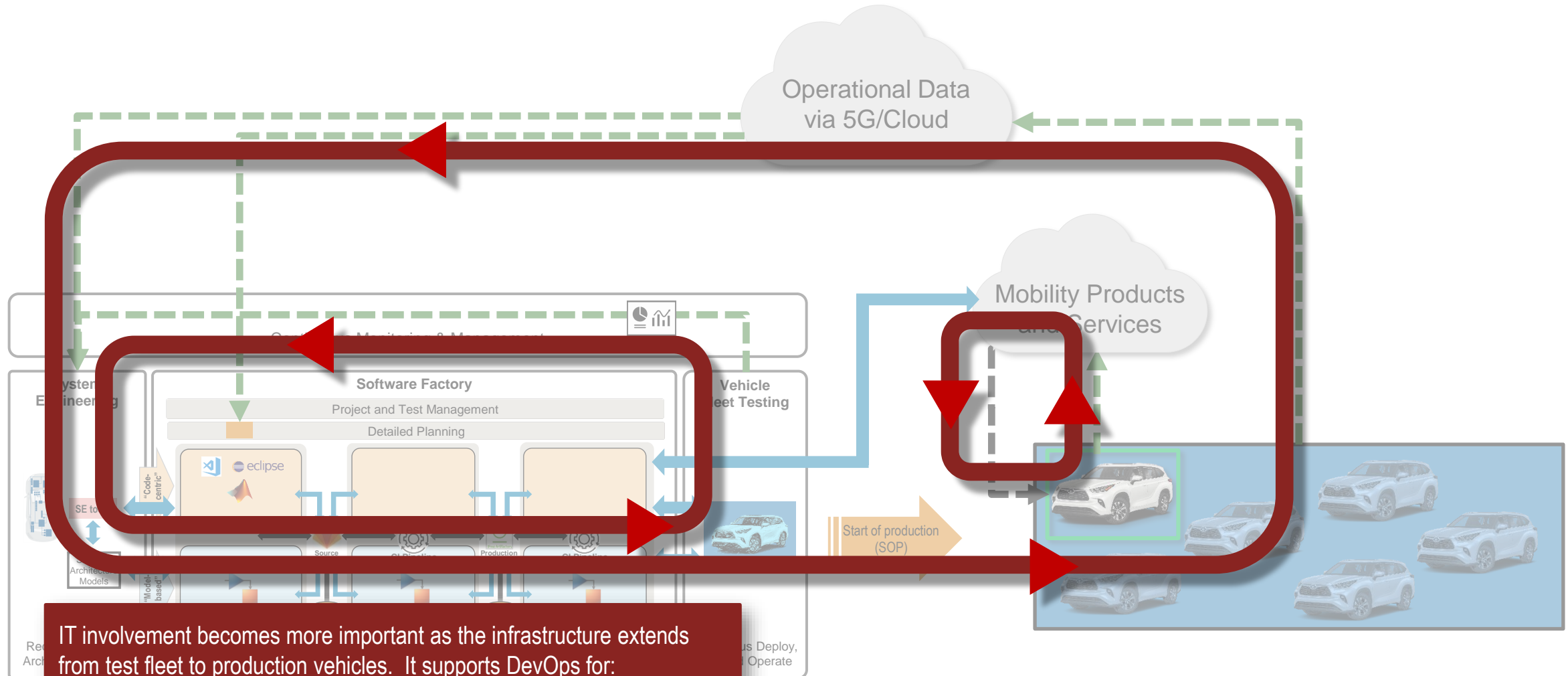
CD =
Continuous
Deployment



These changes are steps to a broader DevOps view



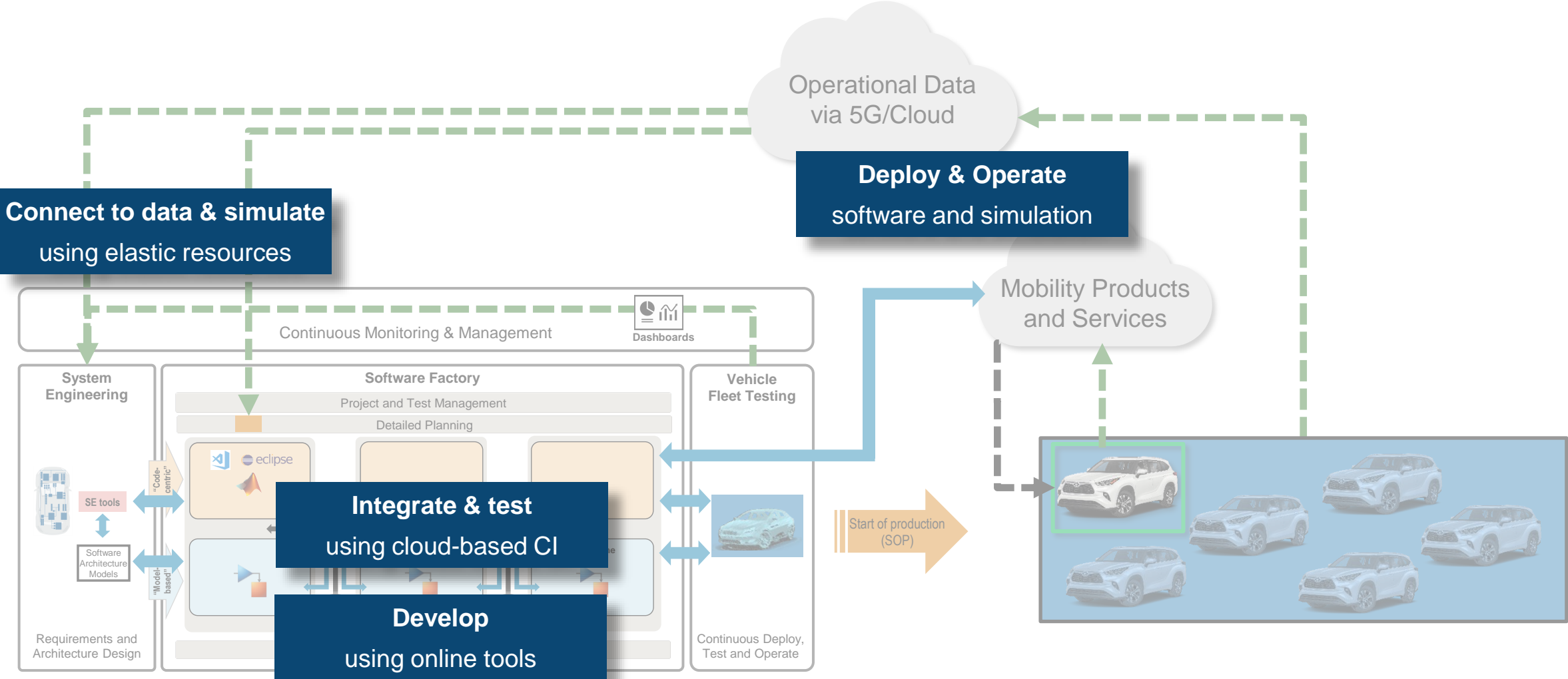
These changes are steps to a broader DevOps view



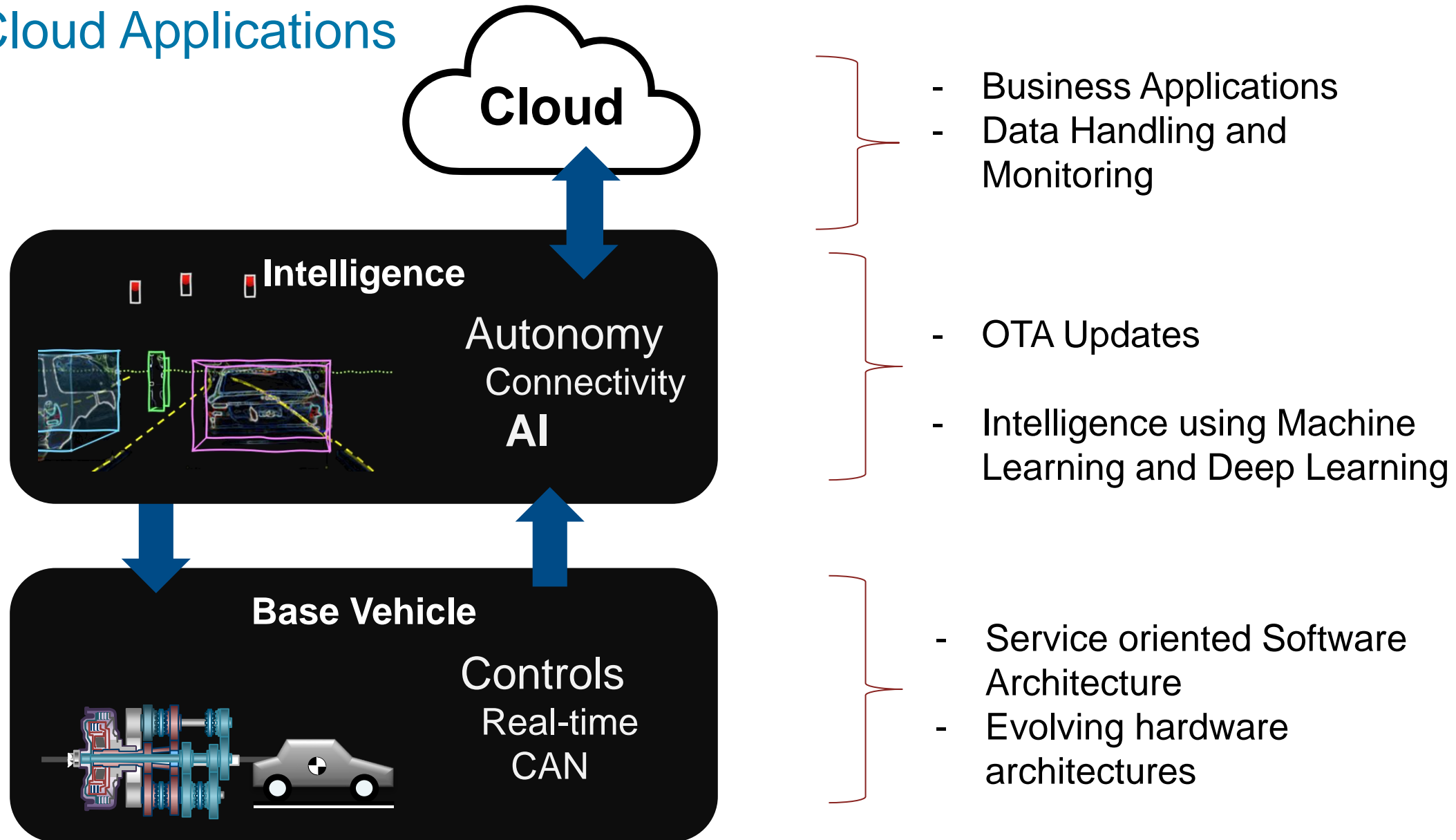
IT involvement becomes more important as the infrastructure extends from test fleet to production vehicles. It supports DevOps for:

1. more effective fleet testing
2. system development and field updates, and
3. support for value-added offerings.

Cloud use case enables a broader DevOps ecosystem



Summary: Software-Defined Vehicles: Workflows for In-Car and Cloud Applications



More Resources: SDV Vision of leading automotive companies

Building the Digital Thread between MBSE and MBD to Meet ISO26262 for Embedded Software

Authors: Joshua McCready (Ford), Hans Gangwar (Ford), Josh Kahn (MathWorks)

Design of vehicle platooning controller with V2V communication

Platooning Controller example + V2V example = Platooning with V2V

Platooning Controller example
 Design Controller for Vehicle Platooning
 Tune spacing controller for trailing vehicles in a platoon using PID Tuner.
 Open Live Script
 Simulink Control Design™ Model-Based PID Controller Tuning R2021b

V2V example
 Intersection Movement Assist Using Vehicle-to-Vehicle Communication
 Design intersection movement assist application using V2V communication.
 Open Example
 Automated Driving Toolbox™ R2022a

THE NEXT LEVEL OF SOFTWARE DEVELOPMENT IN COMMERCIAL VEHICLES

MathWorks AUTOMOTIVE CONFERENCE EUROPE 2022

Dipl.-Ing. Stefan Teuchert
 Senior Vice President
 MAN Truck & Bus SE
 Global Head of Electric/Electronics - Software & Autonomous
 TRATON SE

Pillars of SOA with Simulink & System Composer

Intuitive abstractions consistent with industry practices

Extensible to represent details of your architecture

Precise semantics that allow simulation and code generation

Leverage CI/CD Automation for MBD workflows

Prebuilt & Tailorable Model-Based Design Pipeline

Build system to generate pipeline and optimally execute

Prequalification with Process Advisor

Examples to run process on common CI Systems

R2022a Support Package

STELLANTIS

Applying AI Technologies to Vehicle Sensor Modeling

Authors: Rafael Átila Silva, PhD candidate (Speaker)
 Gustavo Duarte
 Marcelo Lanza
 Ming Yu, PhD.
 Evandro Queiroz

Automotive Conference 2022

Betim, BR
 2022/04/07

MathWorks

Service-Oriented Architectures with Simulink

Call to Action

- Visit us at our demo booth, outside the seminar hall
- Various leading customers have presented their vision (on the previous slide).. Watch the resources and let us know your thoughts
- MathWorks would be happy to collaborate with you for developing your SDV solutions